D-201-100-**11**(1)

SONY.

Color Camera Module

Technical Manual



O 2018 Sony Corporation

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Precautions

Software

Use of the demonstration software developed by Sony Corporation or use of the software with customer developed application software may damage hardware, the application program or the camera. Sony Corporation is not liable for any damages under these conditions.

Operation

Start the camera control software on your computer after you turn on the camera and the image is displayed.

Operation and storage locations

Do not shoot images that are extremely bright (e.g., light sources, the sun, etc.) for long periods of time. Do not use or store the camera in the following extreme conditions:

- Extremely hot or cold places (operating temperature -5 °C to +60 °C (23 °F to 140 °F))
- Close to generators of powerful electromagnetic radiation such as radio or TV transmitters
- Where it is subject to fluorescent light reflections
- Where it is subject to unstable (flickering, etc.) lighting conditions
- Where it is subject to strong vibration
- Where it is subject to radiation from laser beams

Care of the unit

Remove dust or dirt on the surface of the lens with a blower (commercially available).

Other

- Design and specifications are subject to change without notice.
- Do not apply excessive voltage. (Use only the specified voltage.) Otherwise, you may get an electric shock or a fire may occur.
- The CMOS image sensor and IC included in this camera may break if exposed to static electricity. When directly handling this camera, wear an antistatic strap, spread a conductive sheet or similar item under your workbench, and take measures to eliminate static electricity.

• In case of abnormal operation, contact your authorized Sony dealer or the store where you purchased the product.

Handling precautions

- When handling this unit, be careful not to apply an excessive load to all portions of the unit except for the sheet-metal cover. Otherwise, it may result in a failure.
- This unit is designed to be built in the housing. Therefore, take measures to prevent the unit from receiving the intense light such as sunlight directly from the direction other than the front side. Otherwise, it may cause the image quality degradation.

Phenomena specific to CMOS image sensors

The following phenomena that may appear in images are specific to CMOS image sensors. They do not indicate malfunctions.

Rolling shutter

As CMOS image sensors use shutters that capture images line-by-line, there is a slight time difference between the top and bottom of an image. As a result, images may appear skewed if the camera is moved.

White flecks

Although the CMOS image sensors are produced with high-precision technologies, fine white flecks may be generated on the screen in rare cases, caused by cosmic rays, etc.

This is related to the principle of CMOS image sensors and is not a malfunction.

The white flecks especially tend to be seen in the following cases:

- when operating at a high environmental temperature
- when you have raised the master gain (sensitivity)
- when operating in Slow-Shutter mode

Aliasing

When fine patterns, stripes, or lines are shot, they may appear jagged or flicker.

Notes on incorporating a camera

When incorporating a camera on a device that turns ON/OFF 3 times or more a day on average, please release heat so that the temperature rise in the set will not exceed 12 °C by reading the temperature sensor.

Phenomena Specific to Lenses

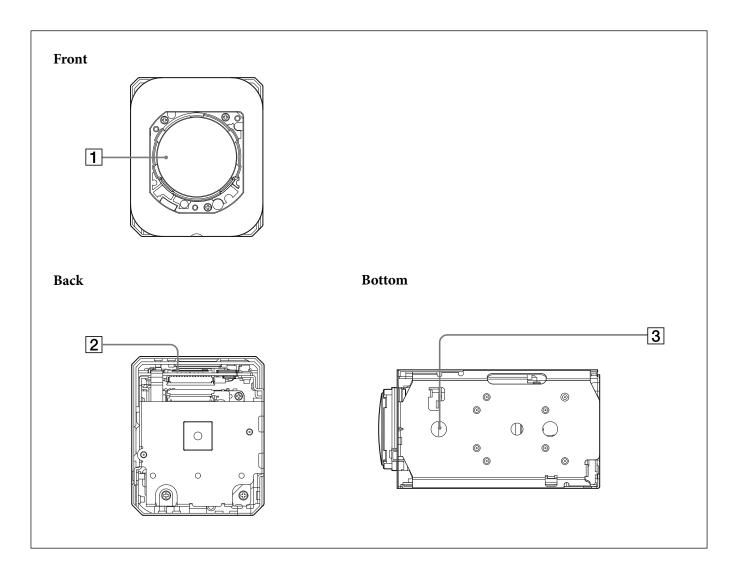
Ghosting

If a strong light source (e.g., the sun) exists near the incidence angle of the lens, bright spots may appear in the image due to diffuse reflection within the lens.

About the trademark

- "Exmor R" and "StableZoom" are trademarks of Sony Corporation.
- The terms HDMI and HDMI High-Definition Multimedia Interface, and the HDMI Logo are trademarks or registered trademarks of HDMI Licensing Administrator, Inc. in the United States and other countries.

Locations of Controls



- 1 Lens
- 2 CN1701 connector
- **3** Tripod screw hole

When a tripod is used, please use 6 mm ($^{1}/_{4}$ in.) or less screw to attach it to the camera. Also, please be sure to attach the tripod securely.

Basic Functions

Overview of Functions

The camera control is performed by VISCA Commands.

In general

• Power On/Off

Powers the camera on and off. Although the screen is set non-displayed when the power is off, the camera is able to accept VISCA Command.

• I/F Clear

Clears the Command buffer of the FCB camera.

Address Set

VISCA is a protocol, which normally supports a daisy chain of up to seven connected cameras via RS-232C interface. In such cases, the address set command can be used to assign addresses from 1 to 7 to each of the seven cameras, allowing you to control the seven cameras with the same personal computer. Although the FCB camera does not support direct connection of cameras in a daisy chain, be sure to use the address set command to set the address whenever a camera is connected for the first time.

• ID Write

Sets the camera ID.

• Mute

Blanks the screen and sends out a synchronizing signal.

• Lens Initialize

Initializes the zoom and focus of the lens. Even when power is turned on, it initializes the zoom and the focus.

Zoom

The FCB camera incorporates a $20 \times$ optical zoom lens combined with a digital zoom function; this camera allows you to zoom up to $240 \times$.

• Optical 20×, f = 27 mm to 540 mm (F 2.0 to F 3.8)

The zoom magnification can be set in the following methods.

Using Standard Mode Using Variable Mode

There are eight levels of zoom speed.

In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.

Direct Mode

Setting the zoom position enables quick movement to the designated position.

Digital Zoom

There are three types of zoom modes; OFF, combined mode and separate mode.

Combined Mode

This is the previously existing zoom method. After the optical zoom has reached its maximum level, the camera switches to Digital Zoom Mode.

Separate Mode

In this mode, Optical Zoom and Digital Zoom can be operated separately. You can use digital zoom magnification at any time from within any level of optical magnification.

In the combined mode, the digital zoom range can be set. A magnified image with less deterioration can be obtained up to $1.5 \times$ in QFHD and $2 \times$ in FHD with the super resolution zoom.

About Continuous Zoom Position Reply

With ZoomDirect mode, or when zooming according to a preset, the camera outputs zoom position data when Continues Zoom Position Reply is set to On via a command.

Continues Zoom Position Reply: y0 07 04 69 0p 0p 0q 0q 0q 0q FF

pp: D-Zoom Position qqqq: Zoom Position

Focus

Focus has the following modes.

Auto Focus Mode

The minimum focus distance is 10 mm at the optical wide end and 1200 mm at the optical tele end, and is independent of the digital zoom.

The Auto Focus (AF) function automatically adjusts the focus position to maximise the high frequency content of the picture in a center measurement area, taking into consideration the high luminance and strong contrast components.

- Normal AF Mode

This is the normal mode for AF operations.

- Interval AF Mode

The mode used for AF movements carried out at particular intervals. The time intervals for AF movements and for the timing of the stops can be set in one-second increments using the Set Time Command. The initial setting for both is set to 5 seconds.

- Zoom Trigger Mode

When zoom position is changed, it becomes AF mode during the pre-set value (initial setting is set to 5 seconds). Then it stops.

• AF Sensitivity

The switching of AF sensitivity can be set.

- Normal

Reaches the highest focus speed quickly. Use this when shooting a subject that moves frequently. Usually, this is the most appropriate mode. - Low

Improves the stability of the focus. When the lighting level is low, the AF function does not take effect, even though the brightness varies, contributing to a stable image.

Manual Focus Mode

Manual Focus has both a Standard Mode and a Variable Mode. Standard Mode focuses at a fixed rate of speed. Variable Mode has eight speed levels.

In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.

One Push Trigger Mode

When a Trigger Command is sent, the lens moves to adjust the focus for the subject. The focus lens then holds that position until the next Trigger Command is input.

• Near Limit

Can be set in a range from $1000 (\infty)$ to F000 (80 mm). Initial setting: B000h (35 cm)

• Spot focus mode

The spot focus mode allows you to focus on a specific portion of the subject. This mode is used when it is difficult to focus on the subject by using the normal auto focus, and so on. The focusing spot is specified by the area of the entire screen divided into 16-split both vertically and horizontally.

White Balance (WB)

White Balance has the following modes.

• Auto

This mode computes the white balance value output using color information from the entire screen. It outputs the proper value using the color temperature radiating from a black subject based on a range of values from 2500K to 7500K. This mode is the initial setting.

• ATW

Auto Tracing White balance (2000K to 10000K)

- Indoor 3200K Base Mode
- Outdoor 5800K Base Mode

• One Push WB

The One Push White Balance mode is a fixed white balance mode that may be automatically readjusted only at the request of the user (One Push Trigger), assuming that a white subject, in correct lighting conditions, and occupying more than 1/2 of the image, is submitted to the camera. One Push White Balance data is lost when the power is turned off. If the power is turned off, reset One Push White Balance.

• Manual WB

This is a mode that enables you to manually set the control of R and B gain up to 256 steps.

Outdoor Auto

This is an auto white balance mode specifically for outdoors. It allows you to capture images with natural white balance in the morning and evening.

• Sodium Vapor Lamp Auto

This is an auto white balance mode that is compatible with sodium vapor lamps.

• **Sodium Vapor Lamp** This is a fixed white balance mode specifically for sodium vapor lamps.

Sodium Vapor Lamp Outdoor Auto

This is an auto white balance mode specifically for outdoors, which is compatible with sodium vapor lamps.

Note

High-pressure sodium lamps are supported. Proper white balance may not be captured for some subjects when using low-pressure sodium lamps.

Auto Exposure Mode (AE)

A variety of AE functions are available for optimal output of subjects in lighting conditions that range from low to high.

• Full Auto

Iris, Gain and Shutter Speed can be set automatically.

• Gain Limit Setting

The gain limit can be set at Full Auto, Shutter Priority, Iris Priority, Bright, Spot Exposure and Manual in AE mode. Use this setting when you want to obtain images with a focus on the signal-to-noise ratio.

• Shutter Priority¹⁾

Adjust with Variable Shutter Speed (1/1 to 1/10,000 sec., 16 high-speed shutter speeds plus 12 low-speed shutter speeds), Auto Iris and Gain.

1) Flicker in the East Japan area (50 Hz power supply frequency) can be eliminated by setting shutter to 1/100s.

• Iris Priority

Adjust with Variable Iris (F2.0 to Close, 22 steps), Auto Gain and Shutter speed

• Gain

Adjust with Variable Gain (0 to 36 dB, 13 steps, 38 steps on High sensitivity mode), Auto Iris and Shutter speed

• Manual

Adjust with Variable Shutter speed, Iris and Gain

Bright

Adjust with Variable Iris and Gain (Close to F2.0, 34 steps and High Sensitivity Mode at 38 steps)

AE – Shutter Priority

The shutter speed can be set freely by the user to a total of 28 steps – 16 high speeds and 12 low speeds. When the slow shutter is set, the speed can be adjusted according to subject brightness. The picture output is read at a normal rate from the memory. The memory is updated at a low rate from the CMOS. AF following capability is lowered and also the number of frame to be displayed is decreased.

In high speed mode, the shutter speed can be set up to 1/10,000s. The iris and gain are set automatically, according to the brightness of the subject.

Data	59.94/29.97 mode	50/25 mode	23.98 mode
21	1/10000	1/10000	1/10000
20	1/6000	1/6000	1/4800
1F	1/4000	1/3000	1/2400
1E	1/3000	1/2500	1/1200
1D	1/2000	1/1750	1/576
1C	1/1500	1/1250	1/400
1B	1/1000	1/1000	1/288
1A	1/725	1/600	1/200
19	1/500	1/425	1/192
18	1/350	1/300	1/144
17	1/250	1/215	1/120
16	1/180	1/150	1/100
15	1/125	1/120	1/96
14	1/100	1/100	1/60
13	1/90	1/60	1/50
12	1/60	1/50	1/48
11	1/50	1/30	1/40
10	1/30	1/25	1/25
0F	1/20	1/20	1/24
0E	1/15	1/15	1/20
0D	1/10	1/12	1/12
0C	1/8	1/8	1/8
0B	1/6	1/6	1/6
0A	1/4	1/4	1/4
9	1/3	1/3	1/3
8	1/2	1/2	1/2
7	2/3	2/3	2/3
6	1/1	1/1	1/1

AE – Iris Priority

The iris can be set freely by the user in 22 steps between F2 and Close.

The gain and shutter speed are set automatically according to the brightness of the subject.

Data	Setting value	Data	Setting value
19	F2	0E	F5.2
18	F2.2	0D	F5.6
17	F2.4	0C	F6.2
16	F2.6	0B	F6.8
15	F2.8	0A	F7.3
14	F3.1	09	F8
13	F3.4	08	F8.7
12	F3.7	07	F9.6
11	F4	06	F10
10	F4.4	05	F11
0F	F4.8	00	CLOSE

AE – Manual

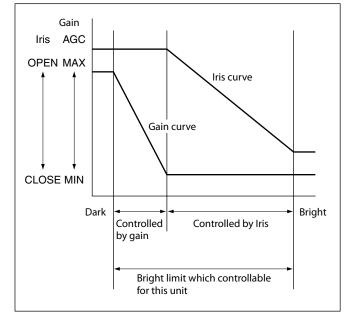
The shutter speed (28 steps), iris (22 steps) and gain (17 steps) can be set freely by the user.

AE – Bright

The bright control function adjusts both gain and iris using an internal algorithm, according to a brightness level freely set by the user. Exposure is controlled by gain when dark, and by iris when bright. As both gain and iris are fixed, this mode is used when

exposing at a fixed camera sensitivity. When switching from Full Auto or Shutter Priority Mode to Bright Mode, the current status will be retained for a short period of time.

Only when the AE mode is set to "Full Auto" or "Shutter Priority," can you switch it to "Bright."



Data	Iris	Gain	Data	Iris	Gain
29*	F2.0	48 dB	16	F2.6	0 dB
28*	F2.0	45 dB	15	F2.8	0 dB
27*	F2.0	42 dB	14	F3.1	0 dB
26*	F2.0	39 dB	13	F3.4	0 dB
25	F2.0	36 dB	12	F3.7	0 dB
24	F2.0	33 dB	11	F4	0 dB
23	F2.0	30 dB	10	F4.4	0 dB
22	F2.0	27 dB	0F	F4.8	0 dB
21	F2.0	24 dB	0E	F5.2	0 dB
20	F2.0	21 dB	0D	F5.6	0 dB
1F	F2.0	18 dB	0C	F6.2	0 dB
1E	F2.0	15 dB	0B	F6.8	0 dB
1D	F2.0	12 dB	0A	F7.3	0 dB
1C	F2.0	9 dB	9	F8.0	0 dB
1B	F2.0	6 dB	8	F8.7	0 dB
1A	F2.0	0 dB	7	F9.6	0 dB
19	F2.0	0 dB	6	F10	0 dB
18	F2.2	0 dB	5	F11	0 dB
17	F2.4	0 dB	00	CLOSE	0 dB

*When high sensitivity mode is on.

When switching from the Shutter Priority mode to the Bright mode, the shutter speed set in the Shutter Priority mode is maintained.

Gain Limit Setting

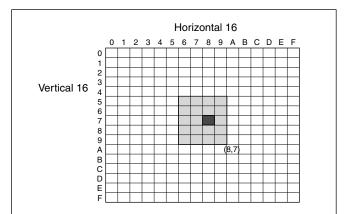
The gain limit can be set at the Full Auto, Shutter Priority and Iris Priority of the Auto Exposure Mode. Use this setting when you want to obtain image in which signal-to-noise ratio is particularly important.

Gain Point Setting

Set the Gain Point in the middle between 0dB and gain limit. The shutter speed can be changed from the point when the set gain value is reached. When you want to obtain the motion-priority image, use this setting.

Spot Exposure Mode

In Full Auto AE, the level for the entire screen is computed and the optimum Auto Iris and Gain levels are determined. In Spot AE, a particular section of the subject can be designated, and then that portion of the image can be weighted and a value is computed so that the Iris and Gain can be optimized to obtain an image. For example, in an image with a lot of movement and with varying levels of brightness, portions without much change can be designated as such a "spot," and changes to the screen can be minimized in that area. As shown in the diagram below, a range of 16 blocks vertically and 16 blocks horizontally can be designated. The level is calculated by the value of the surrounding blocks (shaded) including the designated center block (black). The range of the Spot AE frame is fixed to 5 blocks vertically and 4 blocks horizontally.



Exposure Compensation

Exposure compensation is a function which offsets the internal reference brightness level used in the AE mode, by steps of 1.5 dB.

Data	Step	Setting value
0E	+7	+10.5 dB
0D	+6	+9 dB
0C	+5	+7.5 dB
0B	+4	+6 dB
0A	+3	+4.5 dB
09	+2	+3 dB
08	+1	+1.5 dB
07	0	0 dB
06	-1	-1.5 dB
05	-2	-3 dB
04	-3	-4.5 dB
03	-4	-6 dB
02	-5	-7.5 dB
01	-6	-9 dB
00	-7	-10.5 dB

Slow AE (Auto Exposure)

The slow AE Response function allows you to reduce the exposure response speed. Usually the camera is set up so that the optimum exposure can be obtained automatically within about 1 second. However, using the slow AE response function allows you to lengthen the auto exposure response speed from the initial setup speed (01h) to approx. 10 minutes (30h) (at normal shutter speed).

For example, with the normal setting (about 1 second), if the headlights of a car are caught by the camera, the camera automatically adjusts the exposure so that it can shoot a high-intensity subject (in this case, the headlights). As a result, images around the headlights, that is, the rest of the subject, except the headlights, becomes relatively dark, and poorly distinguished. However, using the slow AE function means the AE response speed will be slower, and response time will be longer. As a result, even if the camera catches a highintensity subject (e.g., the headlights) for a moment, you can still easily distinguish the portions of the image surrounding the headlights.

High Resolution Mode

This mode enhances edges and produces higher definition images.

Aperture Control

Aperture control is a function which adjusts the edge enhancement of objects in the picture. When it is set to Auto, the adjustment is performed automatically.

When it is set to Manual, you can adjust multiple setting items. Sometimes, the noise particle that is generated when the gain is increased becomes noticeable because its edge is enhanced by this function. In this case, lower the edge enhancement level or adjust the edge enhancement amount of noise by "Crispening".

Backlight Compensation

When the background of the subject is too bright, or when the subject is too dark due to shooting in the AE mode, back light compensation will make the subject appear clearer.

Visibility Enhancer (VE)

Depending on the imaging scene, the Visibility Enhancer function makes the darker part of a camera image brighter, and automatically correct brightness and contrast to show bright parts clearly.

Defog mode

When the surrounding area of the subject is foggy and low contrast, the defog mode will make the subject appear clearer.

You can select four levels for this function: OFF, Low, Middle and High.

Highlight Compensation (HLC)

HLC (highlight correction) is a function to adjust AE and AF, and to perform the masking of light area as required when a high intensity spot light is detected. It allows you to easily read the number of vehicles and number plate in the indoor parking area or in the outdoor during the night.

Maximum Shutter Limit

The brighter the object is, the shutter speed will increase. This is the function to set the upper limitation on the shutter speed. This will help to make images smooth with less inconsistent motions when you shoot bright objects.

Minimum Shutter Limit

When the subject becomes dark, the shutter speed becomes slow and the gain is increased. This is a function to put a limit on the shutter speed. It prevents the camera shake when you shoot a moving subject in a dark place.

Noise Reduction (NR)

The NR function removes noise (both random and non-random) to provide clearer images. This function has six steps: levels 1 to 5, plus off. The NR effect is applied in levels based on the gain, and this setting value determines the limit of the effect. In bright conditions, changing the NR level will not have an effect.

When it is set to level 7Fh, you can set NR of 2D/3D individually.

High Sensitivity Mode

In this mode, the maximum gain increases, enabling to obtain a brighter output even in a darker environment. However, if the gain reaches high level, the image will have a large amount of noise.

Variable Gamma Mode

Standard (00h), straight gamma (01h), 512 pattern (02h) are available for setting.

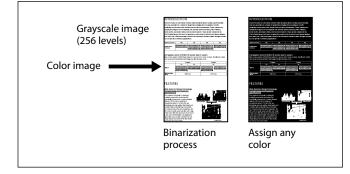
Gamma Offset

You can set the brightness from -16 (00h) to +64 (40h) in each mode of the variable gamma mode.

Color Enhancement

The shot color image can be output in any two colors in the grayscale image based on the density level (brighter or darker than the threshold value) of the image portion.

(The threshold level can be set with an optional level.)



Note

Flicker on images with color enhancement is not a malfunction of the camera. Flicker can be reduced by setting the threshold level and the aperture control.

Temperature Reading Function

The conversion value (hex) of the temperature sensor built into to the camera can be read by using a query command. The conversion value has an error of ± 3 C, and because the temperature sensor is inside the camera, this value is not the ambient temperature. Use it as a reference value.

Slow Shutter On/Off

When set to "On," the slow shutter functions automatically when the light darkens. This setting is available only when the AE mode is set to "Full Auto." The initial setting is "Auto Slow Shutter Off."

Low-Illumination Chroma Suppress Mode

You can configure a chroma suppress mode for lowillumination conditions. This can be useful when color noise is particularly noticeable in such conditions. Four levels (disabled and three levels) are available for the low-illumination chroma suppress mode.

ICR (IR Cut-Removable) Mode

The IR Cut-Filter installed in front of the CMOS image sensor can be engaged or disengaged by the mechanical structure. The sensitivity in the infrared region is increased by disengaging the IR Cut-Filter, allowing the camera to capture the image in darker places. When the auto ICR mode is set to On, the image becomes black and white.

Custom Color Gain

You can configure the color gain. Use this setting when bright color is particularly important. The initial setting 100% (4h) can be set to range from approx. 60% (0h) to 200% (Eh) with 15 stages.

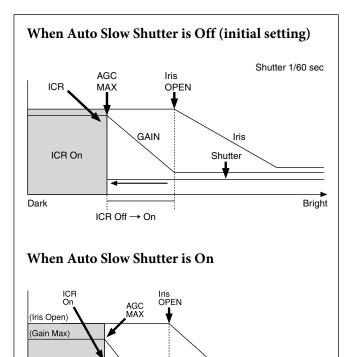
Custom Color Phase

You can configure the color phase. The initial setting 0 degrees (7h) is adjustable between approx. -14 degrees (0h) to +14 degrees (Eh), in 15 increments.

Auto ICR Mode

Auto ICR Mode automatically switches the settings needed for attaching or removing the IR Cut Filter. With a set level of darkness, the IR Cut Filter is automatically disabled (ICR On), and the infrared sensitivity is increased. With a set level of brightness, the IR Cut Filter is automatically enabled (ICR Off). Also, on systems equipped with an IR light, the internal data of the camera is used to make the proper decisions to avoid malfunctions.

Auto ICR Mode operates with the AE Full Auto setting.



Note

Dark

ICB On

(Slow Shutter Max)

Depending on the information such as brightness, etc., in the On/ Off settings condition, a malfunction may occur when the subjects largely consisting of blue and green colors are taken.

GAIN

Adjustable

ICR On → Off Adjustable

Iris

Shutter

(Iris Min) (0 step) (1/60 sec)

Bright

Camera ID

The ID can be set up to 65,536 (0000h to FFFFh). As this will be memorized in the nonvolatile memory inside, data will be saved.

Picture Effect

It consists of the following function.

Black & White: Monochrome Image

Image stabilizer

When the image stabilizer function is set to On, you can obtain the image with less screen blur caused by shaking and so on. The correction effect can be achieved at the vibration frequency around 10 Hz. The image stabilizer function uses the digital zoom method. Although there are changes in the angle of view and resolution, the sensitivity is maintained.

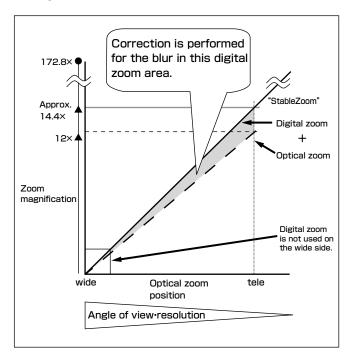
Note

The image stabilizer function may not work under the environment of high frequency vibration components. When using the camera under such environment, set the image stabilizer function to Off.

"StableZoom"

"StableZoom" is a function to perform correction using the image stabilizer function according to the zoom magnification and zoom the image up to approx. 14.4× smoothly by combining the optical zoom with the digital zoom. By zooming the image furthermore using the digital zoom, the image is zoomed up to 172.8×. On the wide side, the image without the deterioration in resolution can be obtained because the digital zoom is not used. On the other hand, the correction effect by the image stabilizer function is maximized on the tele side, reducing the blur.

"StableZoom" can be set to On/Off by the register setting.



Others

E-FLIP

This function reverses the video output from the camera vertically and horizontally.

LR Reverse

This function reverses the video output from the camera horizontally.

Freeze

This function captures an image in the field memory of the camera so that this image can be output continuously.

Because communication inside the camera is based on V cycle, the captured image is always the one 3V to 4Vs after the sending of a Command. Thus, you can not specify a time period after sending EVEN, ODD or a Command.

Electronic Pan/Tilt

In 4K (3840 \times 2160) mode, crop the image at the designated position to Full HD (1920 \times 1080) and display.

You can specify the central coordinate of cropped images by commands. Cropped sizes cannot be changed as it is fixed to FHD.

Memory (Position preset)

Using the position preset function, 16 sets of camera shooting conditions can be stored and recalled. This function allows you to achieve the desired status instantly, even without adjusting the following items each time.

- Zoom Position
- Digital Zoom On/Off/Super Resolution Zoom
- Focus Auto/Manual
- Focus Position
- AE Mode
- Shutter control parameters
- Bright Control
- Iris control parameters
- Gain control parameters
- Exposure Compensation On/Off
- Exposure Level
- Backlight Compensation On/Off
- Slow Shutter On/Off
- White Balance
- R/B Gain
- Aperture Control
- ICR On/Off
- Defog

Custom Preset

As with the position preset function, the camera shooting conditions can be stored and recalled. The settings are recalled when the power is turned on. For setting items, see the "Initial Settings, Custom Preset and Backup" section on page 24.

User Memory Area

A user area of 16 bytes allows you to write data, such as an ID for each customer, data for each system, and so on, freely.

Note

Rewriting of memory is not unlimited. Be careful to avoid using the memory area for such as unnecessary tasks as rewriting the contents of the memory for every operation.

Register Setting

The camera's initial settings can be changed by the register setting command. Register Setting Command: 8x 01 04 24 mm 0p 0q FF mm: Register No. (=00 to 7F) pq: Register Value (=00 to FF) Register Inquiry Command: 8x 09 04 24 mm FF mm: Register No. y0 50 0p 0p FF pp: Register Value (returned from the camera) The register setting items and No. are as follows.

For details, see "Register Setting" on page 55. Baud Rate: 00 Communication speed can be changed. Monitoring Mode: 72 The output mode can be set. Zoom Limit: 50 (wide end), 51 (tele end) The wide and tele zoom limits can be set. D-Zoom Max: 52 The maximum digital zoom limit can be set (initial settinig is $12 \times$). FocusOffset: 55 Placing a dome cover in front of the camera may cause the focal distance of the camera to change. Especially at the Tele end, this effect exceeds the AF range, so focus cannot track, although it responds to changes in this value. For details, see "Register Setting" on page 55.

Extended mode: 5F

ON/OFF can be set. (initial setting is OFF.) For details, see page 17.

Note

After changing the register setting, turn off the camera, then turn it on again.

Privacy Zone Masking Settings

For details, see page 15.

Title Display

- You can set a title of up to 11 lines. One line can contain up to 20 characters.
- You can set display on/off, the horizontal position of the first character, blinking state and color for each line.
- The camera gives priority to a title display when the camera status is displayed on the relevant line. On the lines where a title is not set, the camera status is displayed.

H-position					00h to 0Ah		
	00h to 1Fh						
		00h		WHI	TE		
		01h		YELL			
		02h		VIOL			
Color		03h		REI			
		04h		CYA			
		05h		GRE			
		06h		BLU			
Blink		00h		Of			
		01h		Or			
00 01 02	03	04	05	06	07		
A B C	D	Е	F	G	Н		
08 09 0A	0B	0C	0D	0E	0F		
I J K	L	М	Ν	Ο	Р		
10 11 12	13	14	15	16	17		
Q R S	Т	U	V	W	Х		
18 19 1A	1B	1C	1D	1E	1F		
Y Z &		?	!	1	2		
20 21 22	23	24	25	26	27		
3 4 5	6	7	8	9	0		
28 29 2A	2B	2C	2D	2E	2F		
ÀÈÌ	Ò	Ù	Á	É	Í		
30 31 32	33	34	35	36	37		
Ó Ú Â	Ê	Ô	Æ		Ã		
38 39 3A	3B	3C	3D	3E	3F		
Õ Ñ Ç	ß	Ä	Ï	Ö	Ü		
40 41 42	43	44	45	46	47		
Å \$	¥		£	Ś	i		
48 49 4A	4B	4C	4D	4E	4F		
ø " :	,	•	,	/	-		

Privacy Zone Masking Function

Privacy Zone masking protects private objects and areas such as house windows, entrances, and exits which are within the camera's range of vision but not subject to surveillance.

Privacy zone masking can be masked on the monitor to protect privacy.

Features

- Mask can be set on up to 24 places according to Pan/ Tilt positions.
- Mask can be displayed on 8 places per screen simultaneously.
- Individual on/off zone masking settings.
- Two colors can be individually set for each of 24 privacy zones.
- Interlocking control with zooming.
- Interlocking control with Pan/Tilt.
- Non-interlocking control with Pan/Tilt.

Details of Setting Commands

Set Mask

Command: 8x 01 04 76 mm nn 0r 0r 0s 0s FF **Parameters:**

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 15.
nn	Selects new setting or resetting for the zone. See "nn:
	Setting" in "Parameters" on page 15.
rr	Sets the half value "w" of the Mask Width.
ss	Sets the half value "h" of the Mask Height.
	See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.

Comments: To set the mask, first display the object at the center of the screen. When "nn" is set to 1, the current Pan/Tilt/Zoom Position is recorded in internal memory.

When "nn" is set to 0, the Pan/Tilt/Zoom Position in memory is not changed.

Notes

- The tilt angle at which you can set the mask is between -70 to +70 degrees.
- It is recommended that you set the size to at least twice the size of the object (height and width).

Set Display

Command: 8x 01 04 77 pp pp pp FF **Parameter:**

рр рр рр рр	Each 24 Privacy Zones corresponds to the BIT.
	See "pp pp pp pp: Mask bit" in "Parameters" on
	page 16.

Comments: Each of 24 Privacy zones can be switched on and off individually by a single VISCA Command. If you want to display a Privacy zone, you must set its bit to 1. If you do not want to display a Privacy zone, you must set its bit to 0.

Set Mask Color

Command: 8x 01 04 78 pp pp pp qq rr FF **Parameter:**

рр рр рр рр	Each 24 Privacy Zones correspond to the BIT.
	See "pp pp pp pp: Mask bit" in "Parameters" on
	page 16.
qq	Set the color code
rr	Set the color code. See "qq, rr: Color code" in
	"Parameters" on page 17.

Comments: Two different color masks can be chosen. Two colors can be individually set for each of 24 privacy zones.

If the bit of parameter (pp pp pp pp) is set to "0", mask color will be "qq" color (Color code). If the bit of parameter (pp pp pp pp) is set to "1", the mask color will be "rr" color (Color code).

Example: 8x 01 04 78 00 00 00 03 00 07 FF The mask color of Mask_A and Mask_B is White (color code 07h), and the mask color of the other Mask (C to X) is Black (color code 00h).

Set Pan Tilt Angle

Command: 8x 01 04 79 0p 0p 0p 0q 0q 0q FF **Parameter:**

ррр	Pan Angle
999	Tilt Angle See "Setting pan/tilt angle" in "Parameters" on page 16.
	1.0.1

Comments: Pan/Tilt angle settings are hexadecimal data.

The resolution of Pan/Tilt angle is 0.088 degrees.

Notes

- When you set the pan/tilt angle, locate the pan/tilt position at the center point of the FCB camera's position.
- If you set the pan/tilt angle or zoom the camera, a bigger mask will be displayed for about one second.

Set PTZ Mask

Command: 8x 01 04 7B mm 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r FF

Parameter:

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 16.
ppp	Pan Angle (000 to FFF)
	See "Setting pan/tilt angle" in "Parameters" on page 16.
qqq	Tilt Angle (000 to FFF)
	See "Setting pan/tilt angle" in "Parameters" on page 16.
rrrr	Zoom Position (000 to 4000)
	See "Zoom Ratio and Zoom Position (for reference)" on
	page 53.

Comments: Mask can be set at the desired position by setting the pan tilt angle and zoom position using this command. The set value can be input by hexadecimal number.

Note

Privacy mask zone follows the change of angle of view according to zoom. However, the follow might be delayed for a moment if there is any big change, such as when using D-Zoom or E-FLIP.

Non Interlock Mask

Command: 8x 01 04 6F mm 0p 0p 0q 0q 0r 0r 0s 0s FF

Parameters:

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 15.
pp	Sets the center position "x" of the Mask on screen.
qq	Sets the center position "y" of the Mask on screen.
rr	Sets the half value "w" of the Mask Width.
SS	Sets the half value "h" of the Mask Height.
	See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.

Commands: Mask does not interlock with pan/tilt.

The limitations of parameters are as follows.

(hexadecimal representation)

- x: ±50h
- w: ±50h
- y: ±2Dh
- h: ±2Dh

Note

When the Set Mask command and the Non Interlock Mask command are set to the same mask, the command set later becomes effective.

Parameters

mm: Mask setting list

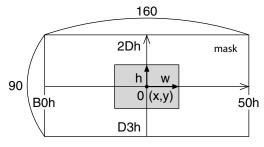
Mask Name	mm (Hex)
Mask_A	00h
Mask_B	01h
Mask_C	02h
Mask_D	03h
Mask_E	04h
Mask_F	05h
Mask_G	06h
Mask_H	07h
Mask_I	08h
Mask_J	09h
Mask_K	0Ah
Mask_L	0Bh

Mask Name	mm (Hex)
Mask_M	0Ch
Mask_N	0Dh
Mask_O	0Eh
Mask_P	0Fh
Mask_Q	10h
Mask_R	11h
Mask_S	12h
Mask_T	13h
Mask_U	14h
Mask_V	15h
Mask_W	16h
Mask_X	17h

nn:Setting

nn	Setting
00h	Resetting the zone size (the value of w,h)
	for the existing mask.
01h	Setting newly the zone size (the value of w,h).

pp: x, qq: y, rr: w, ss: h



Effective display area

Note

The priority order of the mask display is in the sequence from A (highest) to X (lowest).

When you set the parameters of masks non-sequentially, it is recommended that you set the mask whose priority order is higher, first.

pp pp pp pp: Mask bit

	pp								pp							
bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Mask	-	-	Х	W	V	U	Т	S	-	-	R	Q	Р	0	N	М
	pp								pp							
bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Mask	-	-	L	Κ	J	Ι	H	G	-	-	F	E	D	С	В	Α

The "-" must be "0".

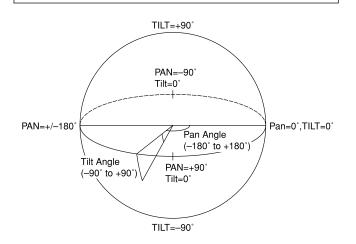
qq, rr: Color code

Mask (color)	Code (qq, rr)	Translucence (qq, rr)				
Black	00 h	10 h				
Gray1	01 h	11 h				
Gray2	02 h	12 h				
Gray3	03 h	13 h				
Gray4	04 h	14 h				
Gray5	05 h	15 h				
Gray6	06 h	16 h				
White	07 h	17 h				
Red	08 h	18 h				
Green	09 h	19 h				
Blue	0A h	1A h				
Cyan	0B h	1B h				
Yellow	0C h	1C h				
Magenta	0D h 1D h					
Mosaic	7F h					

Setting pan/tilt angle

Angle/Parameter of Angle (ppp, qqq)									
-180	-90	0	90	180					
800h	C00h		400h	800h					

Set the angle resolution to 360 (degree)/4096 (1000h).



Extended Commands

Extended commands support the following functions (described previously).

Turn on this mode (for details, see "Extended Mode" in "Register Setting" on page 55) to enable the following functions.

• Exposure Compensation

The setting can be set in steps of approximately 0.2dB (-128 (00h) to approximately +127 (FFh)).

For details, see page 9.

Aperture Control

The setting can be set to 256 levels (00h to FFh). *For details, see page 10.*

Custom Color Gain

The initial setting is 100% (80h), and the setting can be set to 256 levels from approximately 0% (00h) to approximately 200% (FFh).

For details, see page 11.

Custom Color Phase

The initial setting is 0 degrees (80h), and the setting can be set to 256 levels from approximately –14 degrees (00h) to approximately +14 degrees (FFh). *For details, see page 11.*

• Auto ICR Mode

The setting of ICR ON→OFF threshold can be set when Auto ICR is on.

The setting range is 0 step (00h) to 255 step (FFh). The setting of ICR OFF \rightarrow ON threshold (On Level) can be set when Auto ICR is on.

The setting range is 0 step (00h) to 28 step (1Ch). *For details, see page 12.*

Note

When the extended mode is Off, CMD_NOT_EXEC will be returned if you send the extended commands to the camera. When the extended mode is On, CMD_NOT_EXEC will be returned if you send the normal commands to the camera.

External synchronization function (FCB-ER8550)

External synchronization will start when you input synchronization signals to 15pin on CN1701. The possible external synchronization combinations are listed below:

Input External Signal	т	NTSC	PAL		
format Camera Mode	1080/59.94i	1080/50i	1080/47.95i	Black burst	Black burst
3840×2160/29.97p	0	×	×	0	×
3840×2160/25p	×	0	×	×	0
3840×2160/23.98p	×	×	0	×	×
1920×1080/59.94p	0	×	×	0	×
1920×1080/59.94i	0	×	×	0	×
1920×1080/50p	×	0	×	×	0
1920×1080/50i	×	0	×	×	0
1920×1080/29.97p	0	×	×	0	×
1920×1080/25p	×	0	×	×	0
1920×1080/23.98p	×	×	0	×	×
1280×720/59.94p	0	×	×	0	×
1280×720/50p	×	0	×	×	0
720×480/59.94p	0	×	×	0	×
720×576/50p	×	0	×	×	0

External signal spec

- Tri-State SYNC: partial part of SMPTE 240M/274M
- NTSC Black burst: EBU N14/SMPTE RP-154/SMPTE 170M/SMPTE 318M
- PAL Black burst: ITU-R BT.470-6

The H Phase adoption function is not available.

Notes

- Once you input the external synchronization signal, do not change the settings until the state enters the external synchronization mode.
- If the external synchronization signal is not stable, the unit will not enter the external synchronization mode.
- In the cases below, images or data will be disordered and may malfunction.
 - if you input signals other than the allowed external synchronization signals.
 - if you input external synchronization signals when the external synchronization is not supported.
 - if you change the external synchronization signals during video recording.

To change, input the signal again after stopping the recording.

About the firmware update

Overview

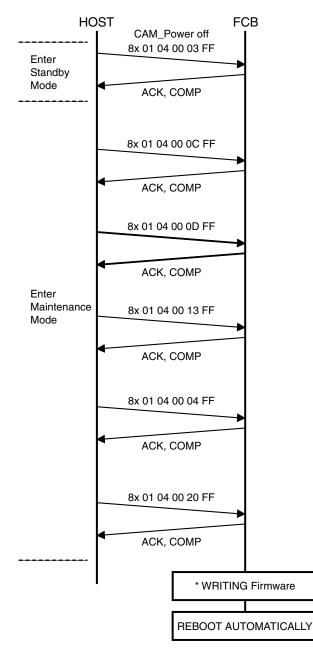
This document descries detailed operation for firmware update.

Serial Port Setting during maintenance mode

Communication Speed	115200 bps
Data bit	8 bit
Parity	None
Stop bit	1 bit
Flow control	None

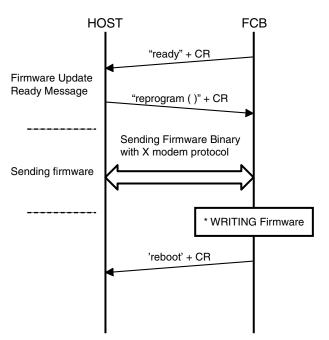
Update Procedure (UART)

Enter Maintenance Mode

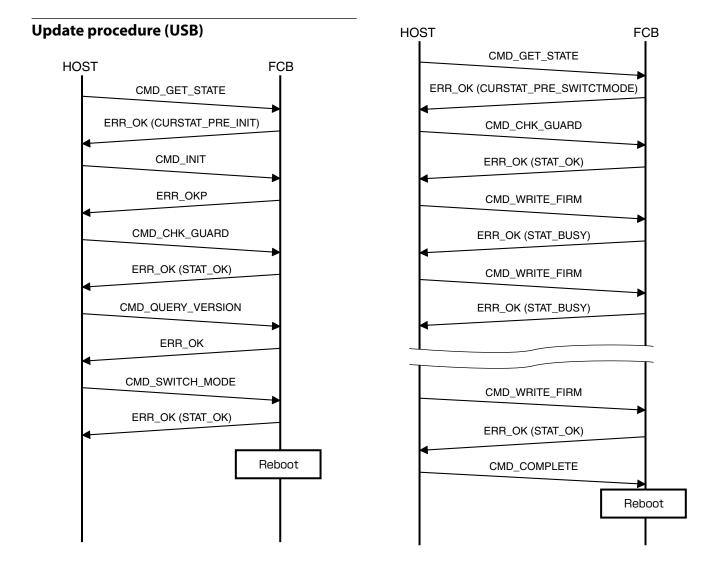


* When power is off during this period, camera will be broken.

Maintenance Mode

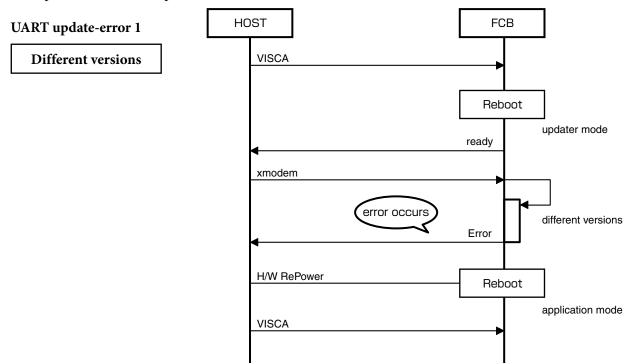


* When power is off during this period, camera will be broken.



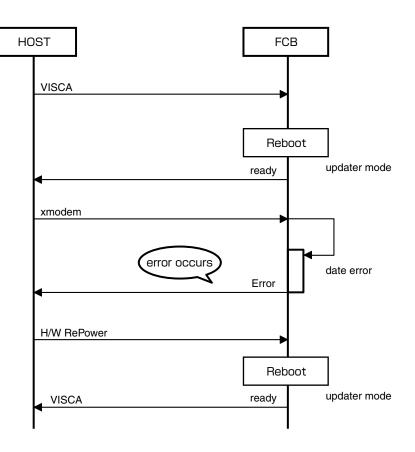
Error occurrence patterns

The update (UART) error patterns are as follows.

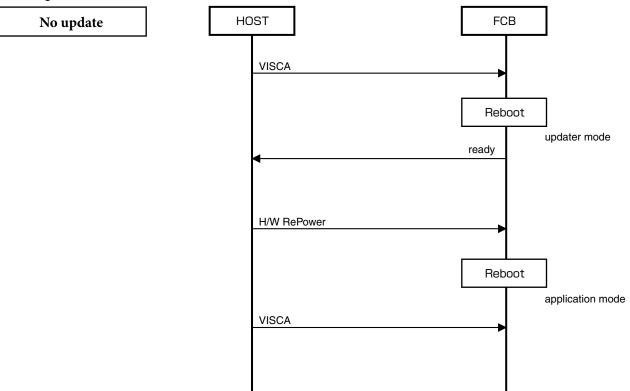


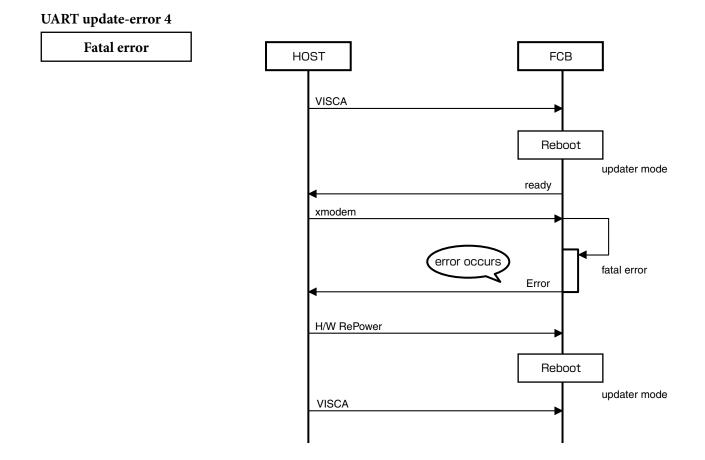
UART update-error 2

Error during update



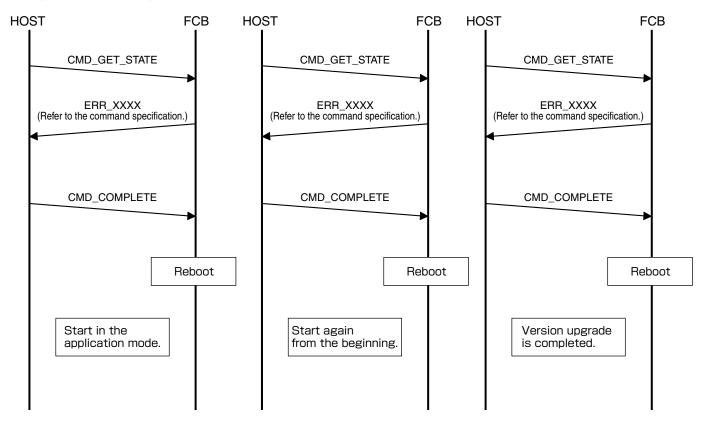
UART update-error 3





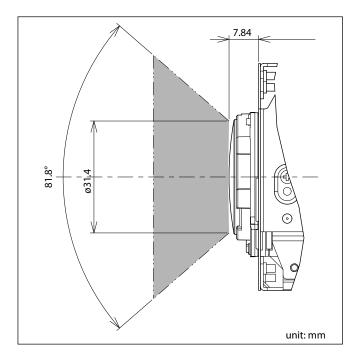
Update Procedure (USB)

The update (USB) error patterns are as follows.

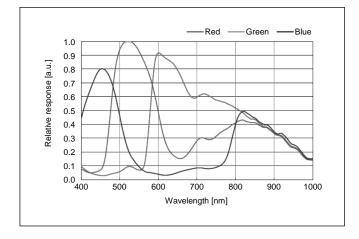


Eclipse

When designing the housing, refer to the dimensional allowance as shown in the figure below.



Spectral Sensitivity Characteristics



Use the graph as a reference value. (We can not guarantee these values.)

This data is measured when the IR cut filter is removed and the characteristics of the lens and optical source characteristics are ignored.

Initial Settings, Custom Preset and Backup

Initial Settings for the various functions of the FCB camera are indicated in the "Initial Settings" column. The "Custom Preset" column indicates whether the custom preset function can be used to store the settings. The function enables the stored settings to be recalled automatically when the camera is turned on. The "Back up at standby" column indicates whether the data is preserved even when the camera is in the standby mode.

Mode/Position setting	Initial Settings	Custom Preset	Back up at standby
Zoom Position	wide end	0	0
D-Zoom On/Off	Off	0	0
D-Zoom Separate/Combine	Combine	0	0
D-Zoom Position	00h	0	0
Focus Position	_	0	0
Focus Auto/Manual	Auto	0	0
Near Limit Setting	B000 (35 cm)	0	0
AF Sensitivity	Normal	0	0
AF Mode	Normal	0	0
AF Run Time	5 sec	0	0
AF Interval	5 sec	0	0
WB Mode	Auto	0	0
WB Data (Rgain, Bgain)	_	0	0
One Push WB Data	_	0	0
AE Mode	Full Auto	0	0
AE Response	01h	0	0
Shutter Position		0	0
Maximum Shutter Limit	1Dh: 1/2000 (59.94 fps)	0	0
	1Dh: 1/2000 (50 fps) 1Dh: 1/30 (29.97 fps) 1Dh: 1/25 (25 fps)	Ũ	
Minimum Shutter Limit	1Eh: 1/48 (23.98 fps) 12h: 1/60 (59.94 fps) 12h: 1/50 (50 fps) 10h: 1/30 (29.97 fps) 10h: 1/25 (25 fps) 12h: 1/48 (23.98 fps)	0	0
Color Enhancement On/Off	Off	0	0
Slow Shutter Limit	0Dh: 1/10 (59.94 fps) 0Dh: 1/10 (29.97 fps) 0Dh: 1/12(50 fps) 0Dh: 1/12(25 fps) 0Dh: 1/12 (23.98 fps)	0	0
Iris Position	19h: F2.0	0	0
Gain Position	01h: 0dB	0	0
Bright Position	_	0	0
Exposure Compensation On/Off	Off	0	0
Exposure Compensation Amount	±0	0	0
BackLight On/Off	Off	0	0

A circle "O" in this column signifies that the data is preserved.

A cross " \times " signifies that the data IS NOT preserved.

Mode/Position setting	Initial Settings	Custom Preset	Back up at standby	
Spot AE On/Off	Off	0	0	
Spot AE Position Setting	X=8, Y=8	0	0	
Detail Level	07h	0	0	
High Resolution Mode On/Off	Off	0	0	
LR Reverse On/Off	Off	0	0	
Freeze On/Off	Off	×	×	
Picture Effect	Off	0	0	
ICR On/Off	Off	0	0	
Auto ICR On/Off	Off	0	0	
Auto ICR Threshold Level	0Eh	0	0	
Camera Memory	Same as the factory value setting	×	0	
Display On/Off	Off	0	0	
Mute On/Off	Off	×	×	
Auto ICR Alarm On/Off	Off	0	0	
NR Level	3	0	0	
Image Stabilizer	Off	0	0	
Gain Limit	Off	0	0	
Color Enhancement Threshold Level	37h	0	0	
Color Enhancement High Luminance Color Setting Y	48h	0	0	
Color Enhancement Low Luminance Color Setting Y	3Ah	0	0	
Low-Illumination Chroma Suppress	1h (Low)	0	0	
Color Gain	4h (100%)	0	0	
Color Hue	7h (0 degrees)	0	0	
Title Display On/Off	Off	0	0	
Title Setting	_	0	0	
Mask Setting	_	0	0	
Mask Color Setting	_	0	0	
Center Line Display On/Off	Off	0	0	
E-Flip On/Off	Off	0	0	
Privacy Zone On/Off	Off	0	0	
Privacy Zone Setting	-	0	0	
Camera ID	0000h	×	0	
ZoomPos Continuous Output On/Off	Off	×	0	
ZoomPos Continuous Output Interval	3Ch	×	0	
HLC Level	Off	0	0	
HLC Mask Level	Off	0	0	

A circle "O" in this column signifies that the data is preserved. A cross " \times " signifies that the data IS NOT preserved.

Notes

- The number of times written to Non-volatile memory (when Custom Preset is executed) is limited.
- Privacy Zone Setting while digital zooming is not preserved by Custom Preset.

Mode Condition

Condition

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Address Set	0	0	0	0	0
IF_Clear	0	0	0	0	0
Command Cancel	0	0	0	0	0
Power On/Off	0	0	0	0	0

Lens

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	Zoom Direct	Focus Direct	ZmFo Direct	Focus Auto
Zoom Tele/Wide/Stop	×	×	0	0	×	×	0	×	0
Zoom Direct	×	×	0	0	×	0	0	×	0
Zoom Focus Direct	×	×	0	0	×	×	×	0	×
D-Zoom On/Off	×	×	0	0	×	×	0	×	0
D-Zoom Separate/Combine	×	×	0	0	×	×	0	×	0
D-Zoom Tele/Wide/Stop	×	X	0	0	×	0	0	0	0
D-Zoom ×1/Max	×	×	0	0	×	0	0	0	0
D-Zoom Direct	×	×	0	0	×	0	0	0	0
Focus Far/Near/Stop	×	×	0	0	×	0	×	×	×
Focus Direct	×	X	0	0	×	0	0	×	×
Focus Auto/Manual	×	×	0	0	×	0	×	×	0
One Push AF	×	×	0	0	×	0	×	×	×
Focus Near Limit	×	×	0	0	×	0	×	×	0
AF Sensitivity Normal/Low	×	×	0	0	×	0	0	0	0
AF Mode Norm/Interval/Zoom	×	X	0	0	×	0	0	0	0
AF Activation Time/Interval Setting	×	×	0	0	×	0	0	0	0
Camera Memory Set/Reset	×	×	0	0	×	×	×	×	0
Camera Memory Recall	×	×	0	0	0	×	×	×	0
Lens Initialize	×	×	0	0	×	×	×	×	0

White Balance

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	WB Auto	Indoor	Outdoor	Outdoor Auto	Sodium Lamp	Sodium Lamp Auto	Sodium Lamp Outdoor Auto	OnePush	ATW	Manual
WB Mode Switchover	×	×	0	0	×	0	0	0	0	0	0	\circ	0	0	\circ
One Push WB	×	×	0	0	×	×	×	×	×	×	×	×	0	X	×
RGain Setting	×	×	0	0	×	×	×	×	×	×	×	X	×	×	0
BGain Setting	×	×	0	0	×	×	×	×	×	×	×	×	×	×	0

Exposure

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	AE Full Auto	AE Manual	Shutter Priority	Iris Priority	Bright
AE Full Auto	×	×	0	0	×	0	0	0	0	0
AE Manual	Х	×	0	0	X	0	0	0	0	0
Shutter Priority	Х	×	0	0	×	0	0	0	0	0
Iris Priority	Х	×	0	0	Х	0	0	0	0	0
Bright	Х	×	0	0	×	×	×	0	×	0
Shutter Setting	×	×	0	0	×	×	0	0	×	×
Iris Setting	Х	×	0	0	×	×	0	×	0	×
Gain Setting	Х	×	0	0	X	×	0	×	X	×
Bright Setting	Х	×	0	0	×	×	×	×	×	0
Auto Slow Shutter On/Off	Х	×	0	0	×	0	0	0	0	0
Exposure Compensation On/Off	Х	×	0	0	×	0	0	0	0	0
Exposure Compensation Setting	×	×	0	\bigcirc	×	0	0	0	0	0
BackLight On/Off	Х	×	0	\bigcirc	×	0	0	0	\bigcirc	0
SpotAE On/Off	×	×	0	\bigcirc	×	0	\circ	0	\circ	0
SpotAE Setting	Х	×	0	\bigcirc	×	\circ	\circ	0	\circ	0
Defog On/Off	Х	×	0	0	0	0	0	0	0	0
Minimum Shutter On/Off	Х	×	0	0	×	0	0	0	0	0
VE On/Off	Х	×	0	0	×	0	0	0	0	0
HLC Setting (On/Off/Mask Level)	×	×	0	0	×	0	0	0	0	0

Others

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Aperture Setting	×	×	0	0	×
High Resolution Mode On/Off	×	×	0	0	0
LR_Reverse On/Off	×	×	0	0	0
Freeze On/Off	×	×	0	0	0
Picture Effect Setting	×	×	0	0	0
ICR On/Off	×	×	0	0	0
Auto ICR On/Off	X	Х	0	0	×
Auto ICR Threshold Level Setting	×	×	0	0	0
Auto ICR Alarm On/Off	×	0	0	0	0
Display On/Off	×	×	0	0	0
Mute On/Off	×	×	0	0	0
Title Setting	×	×	0	0	0
Mask On/Off	×	×	0	\bigcirc	0
Mask Setting	×	×	0	\bigcirc	0
MD On/Off	×	×	\bigcirc	\bigcirc	0
ID Write	×	×	0	0	0
Memory Save	×	×	0	0	0
Register Value Setting	×	Х	0	0	0
Color Enhancement On/Off	X	Х	0	0	0
NR Level Setting	X	Х	0	0	0
Chroma Suppress	×	Х	0	0	0
Color Gain	×	×	0	0	0
Color Hue	×	×	0	0	0

Command List

VISCA/RS-232C Commands

This Manual outlines an RS-232C control protocol and command list for certain Sony cameras from which control software can be developed. THIS CONTROL PROTOCOL AND COMMAND LIST IS PROVIDED BY SONY ON AN "AS-IS BASIS" WITHOUT WARRANTY OF ANY KIND. SONY DOES NOT WARRANT ANY PARTICULAR RESULT FROM THE USE OF THIS CONTROL PROTOCOL AND COMMAND LIST AND DISCLAIMS AND EXCLUDES ALL WARRANTIES. EXPRESS OR IMPLIED, WITH RESPECT TO THAT CONTROL PROTOCOL AND COMMAND LIST, INCLUDING, BUT NOT LIMITED TO, ANY OR ALL IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. IN FACT, SONY SPECIFICALLY ACKNOWLEDGES THAT SOFTWARE DEVELOPED BASED ON THIS CONTROL PROTOCOL AND COMMAND LIST MAY CAUSE MALFUNCTION OR DAMAGE TO HARDWARE AND SOFTWARE USED WITH IT (INCLUDING SONY HARDWARE AND SOFTWARE) AND SPECIFICALLY DISCLAIMS ANY LIABILITY FOR ANY SUCH MALFUNCTION OR DAMAGE. THIS CONTROL PROTOCOL AND COMMAND LIST SHOULD BE USED WITH CAUTION.

Overview of VISCA

In VISCA, the device outputting commands, for example, a computer, is called the controller. The device receiving the commands, an FCB camera is called the peripheral device. In VISCA, up to seven peripheral devices like the FCB camera can be connected to one controller using communication conforming to the RS-232C standard. The parameters of RS-232C are as follows.

- Communication speed: 9.6 kbps/19.2 kbps/ 38.4 kbps/115.2 kbps
- Data bits : 8
- Start bit : 1
- Stop bit : 1
- Non parity

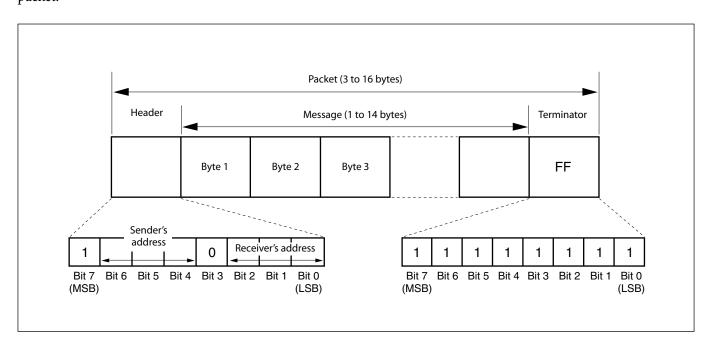
Flow control using XON/XOFF and RTS/CTS, etc., is not supported.

VISCA Communication Specifications

VISCA packet structure

The basic unit of VISCA communication is called a packet. The first byte of the packet is called the header and comprises the sender's and receiver's addresses. For example, the header of the packet sent to the FCB camera assigned address 1 from the controller (address 0) is hexadecimal 81h. The packet sent to the camera assigned address 2 is 82h. In the command list, as the header is 8X, input the address of the camera assigned address 1 is 90h. The packet from the camera assigned address 2 is A0h.

Some of the commands for setting cameras can be sent to all devices at one time (broadcast). In the case of broadcast, the header should be hexadecimal 88h. When the terminator is FFh, it signifies the end of the packet.



Command and inquiry

Command

Sends operational commands to the FCB camera.

Inquiry

Used for inquiring about the current state of the FCB camera.

	Command Packet	Note
Inquiry	8X QQ RR FF	$QQ^{1)} = Command/Inquiry,$
		RR ²⁾ = category code
¹⁾ QQ = 01	(Command), 09 (Inquiry)	

²⁾ RR = 00 (Interface), 04 (camera 1), 06 (Pan/Tilt), 07 (camera 2)

X = 1 to 7: FCB camera address

Responses for commands and inquiries

• Acknowledge message

Returned by the FCB camera when it receives a command. No Acknowledge message is returned for inquiries.

• Completion message

Returned by the FCB camera when execution of commands or inquiries is completed. In the case of inquiry commands, it will contain reply data for the inquiry after the 3rd byte of the packet. If the Acknowledge message is omitted, the socket number will contain 0.

Reply Packete

AcknowledgeX0 4Y FFCompletion (Commands)X0 5Y FFCompletion (Inquiries)X0 5Y ... FFX = 9 to F: FCB camera address + 8, Y = socket number

• Error message

When a command could not be executed or failed, an error message is returned instead of the Acknowledge message. After an Acknowledge message, an error message may be returned if the process of some command (zoom, etc.) has not been completed.

When a inquiry command could not be executed or failed, an error message is returned instead of the completion message.

Error Packet	Description			
X0 6Y 01 FF	Message length error (>14 bytes)			
X0 6Y 02 FF	Syntax Error			
X0 6Y 03 FF	Command buffer full			
X0 6Y 04 FF	Command cancelled			
X0 6Y 05 FF	No socket (to be cancelled)			
X0 6Y 41 FF	Command not executable			
X = 9 to F: FCB camera address + 8, Y = socket number				

Socket number

When command messages are sent to the FCB camera, send the next command message after waiting for the completion message or error message to return. However to deal with advanced uses, the FCB camera has two buffers (memories) for commands, so that up to two commands including the commands currently being executed can be received. When the FCB camera receives commands, it notifies the sender which command buffer was used using the socket number of the Acknowledge message. As the completion message or error message also has a socket number, it indicates which command has ended. Even when two command buffers are being used at any one time, an FCB camera management command and some inquiry messages can be executed. The Acknowledge message is not returned for these commands and inquiries, and only the completion message of socket number 0 is returned.

Command execution cancel

To cancel a command which has already been sent, send the Cancel command as the next command. To cancel one of any two commands which have been sent, use the cancel message.

Cancel Packet

Cancel 8X 2Y FF X = 1 to 7: FCB camera address, Y = socket number

An error message will be returned for this command, but this is not a fault. It indicates that the command has been canceled.

VISCA Command/Acknowledge Protocol

Command	Command Message	Reply Message	Comments
General Command	81 01 04 38 02 FF	90 41 FF (Acknowledge)	Returns Acknowledge when a command has been accepted, and
	(Example)	+90 51 FF (Completion)	Completion when a command has been executed.
		90 4 <u>2</u> FF 90 5 <u>2</u> FF	
	81 01 04 38 FF	90 60 02 FF (Syntax Error)	Accepted a command which is not supported or a command
	(Example)		lacking parameters.
	81 01 04 38 02 FF	90 60 03 FF	There are two commands currently being executed, and the
	(Example)	(Command Buffer Full)	command could not be accepted.
	81 01 04 08 02 FF	90 61 41 FF	Could not execute the command in the current mode.
	(Example)	(Command Not Executable)	
		90 6 <u>2</u> 41 FF	
Inquiry Command	81 09 04 38 FF	90 50 02 FF (Completion)	Acknowledge is not returned for the inquiry command.
	(Example)		
	81 09 05 38 FF	90 60 02 FF (Syntax Error)	Accepted an incompatible command.
	(Example)		
Address Set	88 30 <u>01</u> FF	88 30 <u>02</u> FF	Returned the device address to +1.
IF_Clear(Broadcast)	88 01 00 01 FF	88 01 00 01 FF	Returned the same command.
IF_Clear (For x)	8x 01 00 01 FF	z0 50 FF (Completion)	Acknowledge is not returned for this command.
Command Cancel	8x 2y FF	z0 6y 04 FF	Returned when the command of the socket specified is canceled.
		(Command Canceled)	Completion for the command canceled is not returned.
		z0 6y 05 FF (No Socket)	Returned when the command of the specified socket has already
			been completed or when the socket number specified is wrong.

VISCA Camera-Issued Messages

Acknowledge/Completion Messages

	Command Messages	Comments
Acknowledge	z0 4y FF	Returned when the command is accepted.
	(y:Socket No.)	
Completion	z0 5y FF	Returned when the command has been executed.
	(y:Socket No.)	

z = Device address + 8

Error Messages

	Command Messages	Comments
Syntax Error	z0 60 02 FF	Returned when the command format is different or when a command with illegal
		command parameters is accepted.
Command Buffer Full	z0 60 03 FF	Indicates that two sockets are already being used (executing two commands) and the
		command could not be accepted when received.
Command Canceled	z0 6y 04 FF	Returned when a command which is being executed in a socket specified by the cancel
	(y:Socket No.)	command is canceled. The completion message for the command is not returned.
No Socket	z0 6y 05 FF	Returned when no command is executed in a socket specified by the cancel command,
	(y:Socket No.)	or when an invalid socket number is specified.
Command Not Executable	z0 6y 41 FF	Returned when a command cannot be executed due to current conditions. For example,
	(y:Socket No.)	when commands controlling the focus manually are received during auto focus.

Network Change Message

	Command Message	Comments
Network Change	z0 38 FF	Issued when power is being routed.

FCB Camera Commands

Command List (1/7)

Command Set	Command	Command Packet	Comments
AddressSet	Broadcast	88 30 0p FF	Address Setting p:Address
IF_Clear	-	8x 01 00 01 FF	I/F Clear
	Broadcast	88 01 00 01 FF	
CommandCancel	-	8x 2p FF	p: Socket No. (=1 or 2)
CAM_Power	On	8x 01 04 00 02 FF	Power On/Off
	Off (Standby)	8x 01 04 00 03 FF	
CAM_Zoom	Stop	8x 01 04 07 00 FF	-
	Tele (Standard)	8x 01 04 07 02 FF	
	Wide (Standard)	8x 01 04 07 03 FF	
	Tele (Variable)	8x 01 04 07 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 07 3p FF	
	Direct	8x 01 04 47 0p 0q 0r 0s FF	pqrs: Zoom Position
			Min. 0000h
			Max. 4000h (In Separate mode)
			Max. 4000h (In Combine mode and DZoom=Off)
			Max. 5556h (In Combine mode, DZoom=Super Resolution Zoom, and monitoring mode QFHD)
			Max. 6000h (In Combine mode, DZoom=Super Resolution
			Zoom, and monitoring mode FHD or less)
			Max. 7AC0h (In Combine mode and DZoom=On)
CAM_DZoom	On	8x 01 04 06 02 FF	Digital Zoom On/Off/Super Resolution Zoom
	Off	8x 01 04 06 03 FF	
	Super Resolution Zoom	8x 01 04 06 04 FF	
	Combine Mode	8x 01 04 36 00 FF	Optical/Digital Zoom Combined
	Separate Mode	8x 01 04 36 01 FF	Optical/Digital Zoom Separate
	Stop	8x 01 04 06 00 FF	-
	Tele (Variable)	8x 01 04 06 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 06 3p FF	* Enabled during Separate Mode
	x1/Max	8x 01 04 06 10 FF	x1/MAX Magnification Switchover
			* Enabled during Separate Mode
	Direct	8x 01 04 46 00 00 0p 0q FF	pq: D-Zoom Position (00h to EBh) * Enabled during Separate Mode
CAM_Focus Mode	Auto Focus	8x 01 04 38 02 FF	AF On/Off
Chivi_1 ocus mode	Manual Focus	8x 01 04 38 03 FF	
	Auto/Manual	8x 01 04 38 10 FF	—
CAM_Focus	Stop	8x 01 04 08 00 FF	
	Far (Standard)	8x 01 04 08 02 FF	—
	Near (Standard)	8x 01 04 08 03 FF	—
	Far (Variable)	8x 01 04 08 2p FF	p=0 (Low) to 7 (High)
	Near (Variable)	8x 01 04 08 3p FF	
	Direct	8x 01 04 48 0p 0q 0r 0s FF	pqrs: Focus Position 0000h to F000h
	One Push Trigger	8x 01 04 18 01 FF	One Push AF Trigger
	Near Limit	8x 01 04 28 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position 1000h to F000h
CAM_AFMode	Normal AF	8x 01 04 57 00 FF	AF Movement Mode
CAM_AFMode	Interval AF	8x 01 04 57 01 FF	
		1	
	Zoom Trigger AF	8x 01 04 57 02 FF	

Command List (2/7)

Command Set	Command	Command Packet	Comments
CAM_SpotFocus	On	8x 01 05 08 02 FF	pq: X (0h to Fh), rs: Y (0h to Fh)
	Off	8x 01 05 08 03 FF	
	Position	8x 01 05 68 0p 0q 0r 0s FF	
CAM_AFSensitivity	Normal	8x 01 04 58 02 FF	AF Sensitivity switching
	Low	8x 01 04 58 03 FF	
CAM_IRCorrection	Standard	8x 01 04 11 00 FF	Focus IR compensation data switching
	IR Light	8x 01 04 11 01 FF	
CAM_ZoomFocus	Direct	8x 01 04 47 0p 0q 0r 0s	pqrs: Zoom Position
CAM_Initialize	Lens	0t 0u 0v 0w FF 8x 01 04 19 01 FF	tuvw: Focus Position Lens Initialization Start
CAM_Initialize	Camera		Camera reset
CAM_WB		8x 01 04 19 03 FF 8x 01 04 35 00 FF	Normal Auto
CAM_WB	Auto		
	Indoor	8x 01 04 35 01 FF	Indoor mode
	Outdoor	8x 01 04 35 02 FF	Outdoor mode
	One Push WB	8x 01 04 35 03 FF	One Push WB mode
	ATW	8x 01 04 35 04 FF	Auto Tracing White Balance
	Manual	8x 01 04 35 05 FF	Manual Control mode
	Outdoor Auto	8x 01 04 35 06 FF	Outdoor auto
	Sodium Lamp Auto	8x 01 04 35 07 FF	Auto including sodium lamp source
	Sodium Lamp	8x 01 04 35 08 FF	Sodium lamp source fixed mode
	Sodium Lamp Outdoor	8x 01 04 35 09 FF	Outdoor auto including sodium lamp source
CAM_WBTrigger	Auto One Push Trigger	8x 01 04 10 05 FF	One Push WB Trigger
CAM_RGain	Reset	8x 01 04 03 00 FF	Manual Control of R Gain
CAM_RGain		8x 01 04 03 02 FF	
	Up		
	Down	8x 01 04 03 03 FF	pq: R Gain 00h to FFh
CAM DOute	Direct	8x 01 04 43 00 00 0p 0q FF	Manual Control of B Gain
CAM_BGain	Reset	8x 01 04 04 00 FF	Manual Control of B Gain
	Up	8x 01 04 04 02 FF	
	Down	8x 01 04 04 03 FF	
	Direct	8x 01 04 44 00 00 0p 0q FF	pq: B Gain 00h to FFh
CAM_AE	Full Auto	8x 01 04 39 00 FF	Full Auto
	Manual	8x 01 04 39 03 FF	Manual Control mode
	Shutter Priority	8x 01 04 39 0A FF	Shutter Priority Auto Exposure mode
	Iris Priority	8x 01 04 39 0B FF	Iris Priority Auto Exposure mode
	Gain Priority	8x 01 04 39 0E FF	Gain Priority Auto Exposure mode
	Bright	8x 01 04 39 0D FF	Bright Mode (Manual control)
CAM_	On	8x 01 05 39 02 FF	p: Position
LowLightBasisBrightness	Off	8x 01 05 39 03 FF	
	Position	8x 01 05 49 0p FF	
CAM_Shutter	Reset	8x 01 04 0A 00 FF	Shutter Setting
	Up	8x 01 04 0A 02 FF	
	Down	8x 01 04 0A 03 FF	
	Direct	8x 01 04 4A 00 00 0p 0q FF	pq: Shutter Position
CAM_MaxShutter	Limit	8x 01 05 2A 00 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutter	Limit	8x 01 05 2A 01 0p 0q FF	pq: Low-speed shutter limit

Command List (3/7)

Command Set	Command	Command Packet	Comments		
CAM_SlowShutter	On	8x 01 04 5A 02 FF	Slow Shutter On/Off		
	Off	8x 01 04 5A 03 FF			
	Limit	8x 01 05 5A 0p 0q FF	pq: Slow Shutter Limit		
CAM_Iris	Reset	8x 01 04 0B 00 FF	Iris Setting		
	Up	8x 01 04 0B 02 FF	_		
	Down	8x 01 04 0B 03 FF	_		
	Direct	8x 01 04 4B 00 00 0p 0q FF	pq: Iris Position		
CAM_Gain	Reset	8x 01 04 0C 00 FF	Gain Setting		
	Up	8x 01 04 0C 02 FF			
	Down	8x 01 04 0C 03 FF			
	Direct	8x 01 04 4C 00 00 0p 0q FF	pq: Gain Position		
	Gain Limit	8x 01 04 2C 0p FF	p: Gain Limit		
	Gain Point Pos	8x 01 05 4C 0p 0q FF	pq: Gain Point		
	Gain Point On/Off	8x 01 05 0C 0p FF	p:2=On, 3=Off		
CAM_Bright	Reset	8x 01 04 0D 00 FF	Bright Setting		
	Up	8x 01 04 0D 02 FF			
	Down	8x 01 04 0D 03 FF			
	Direct	8x 01 04 4D 00 00 0p 0q FF	pq: Bright Position		
CAM_ExpComp	On	8x 01 04 3E 02 FF	Exposure Compensation On/Off		
	Off	8x 01 04 3E 03 FF	1		
	Reset	8x 01 04 0E 00 FF	Exposure Compensation Amount Setting		
	Up	8x 01 04 0E 02 FF			
	Down	8x 01 04 0E 03 FF			
	Direct	8x 01 04 4E 00 00 0p 0q FF	pq: ExpComp Position 00h to 0Eh		
CAM_Backlight	On	8x 01 04 33 02 FF	Back Light Compensation On/Off		
	Off	8x 01 04 33 03 FF			
CAM_SpotAE	On	8x 01 04 59 02 FF	Spot Auto Exposure Setting		
	Off	8x 01 04 59 03 FF			
	Position	8x 01 04 29 0p 0q 0r 0s FF	pq: X (0h to Fh), rs: Y (0h to Fh)		
CAM_AE_Response	Direct	8x 01 04 5D pp FF	pp: Auto Exposure Response Setting (01h to 30h), default value: 01h		
CAM_VE	Off	8x 01 04 3D 03 FF	VE Off		
	VE On	8x 01 04 3D 06 FF	VE On		
	Set Parameter	8x 01 04 2D 00 0q 0r 0s 00 00 00	q: Display brightness level (0: Dark to 6: Bright)		
		00 FF	r: Brightness compensation selection (0: Very dark, 1: Dark, 2: Standard, 3: Bright)s: Compensation level (0: Low, 1: Mid, 2: High)		
CAM_Defog	On	8x 01 04 37 02 0p FF	Defog On/Off		
	Off	8x 01 04 37 03 00 FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)		

Command List (4/7)

Command Set	Command	Command Packet	Comments			
CAM_Aperture	Reset	8x 01 04 02 00 FF	Aperture Control			
	Up	8x 01 04 02 02 FF				
	Down	8x 01 04 02 03 FF				
	Level	8x 01 04 42 00 00 0p 0q FF	pq: Aperture Gain (00h to 0Fh)			
	Mode	8x 01 05 42 01 0p FF	p: Auto (0)/Manual (1) selection			
	BandWidth	8x 01 05 42 02 0p FF	 p: Bandwidth setting 0: default (initial value) 1: low bandwidth 2: mid bandwidth 3: wide bandwidth 4: broad bandwidth 			
	Crispening	8x 01 05 42 03 0p FF	p: Crispening (0h to 7h)			
	H/V balance	8x 01 05 42 04 0p FF	p: H/V Balance (5h to 9h)			
	B/W balance	8x 01 05 42 05 0p FF	p: B/W Balance (0h to 4h)			
	Limit	8x 01 05 42 06 0p FF	p: Limit (0h to 7h)			
	HighLightDetail	8x 01 05 42 07 0p FF	p: High light detail (0h to 4h)			
	SuperLow	8x 01 05 42 08 0p FF	p: Super low emphasis (0h to 7h)			
CAM_HR	On	8x 01 04 52 02 FF	High Resolusion Mode On/Off			
	Off	8x 01 04 52 03 FF				
CAM_NR	Noise Reduction	8x 01 04 53 pp FF	p: NR setting (00h: Off, 01h to 05h: level, 7Fh: 2D/3D manual setting)			
	2D NR/3D NR	8x 01 05 53 0p 0q FF	p: 2D NR level (0h to 5h), q: 3D NR level (0h to 5h)			
CAM_Stabilizer	On	8x 01 04 34 02 FF	Image Stabilizer On/Off			
	Off	8x 01 04 34 03 FF				
CAM_Gamma	—	8x 01 04 5B 0p FF	p: Gamma Setting (0: Standard, 1: Straight, 2: Pattern)			
	Pattern	8x 01 05 5B 0p 0q 0r FF	pqr: Selection pattern (001h to 200h)			
	Offset	8x 01 04 1E 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 40h)			
CAM_HighSensitivity	On	8x 01 04 5E 02 FF	High Sensitivity mode On/Off			
Critic_ringhoensitivity	Off	8x 01 04 5E 03 FF				
CAM_LR_Reverse	On	8x 01 04 61 02 FF	LR Reverse On/Off			
OTHN_ERCIRCYCLOC	Off	8x 01 04 61 03 FF				
CAM_Freeze	On	8x 01 04 62 02 FF	Freeze On/Off			
	Off	8x 01 04 62 03 FF				
CAM PictureEffect	Off	8x 01 04 63 00 FF	Picture Effect Setting			
	Black & White	8x 01 04 63 04 FF				
CAM_PictureFlip	On	8x 01 04 66 02 FF	E-Flip On/Off			
I	Off	8x 01 04 66 03 FF				
CAM_ICR	On	8x 01 04 01 02 FF	ICR Mode On/Off			
_	Off	8x 01 04 01 03 FF				
CAM_AutoICR	On	8x 01 04 51 02 FF	Auto ICR Mode On/Off			
_	Off	8x 01 04 51 03 FF				
	Threshold	8x 01 04 21 00 00 0p 0q FF	pq: ICR On \rightarrow Off Threshold Level (00h to FFh)			
CAM	On	8x 01 04 31 02 FF	Auto ICR switching Alarm On/Off			
_AutoICRAlarmReply	Off	8x 01 04 31 03 FF				
	(Reply)	y0 07 04 31 02 FF	ICR Off \rightarrow On			
	//	y0 07 04 31 03 FF	$\frac{\text{ICR Off} \to \text{On}}{\text{ICR On} \to \text{Off}}$			

Command List (5/7)

Command	Command Packet	Comments				
Reset	8x 01 04 3F 00 pp FF	pp: Memory Number (=0h to 63h)				
Set	8x 01 04 3F 01 pp FF					
Recall	8x 01 04 3F 02 pp FF					
Reset	8x 01 04 3F 00 7F FF	Starts up in this mode when the power is turned on.				
Set	8x 01 04 3F 01 7F FF	1				
Recall	8x 01 04 3F 02 7F FF					
Write	8x 01 04 23 0X 0p 0q 0r 0s FF	X: 00h to 07h (Address), total 16 byte				
	1 1	pqrs: 0000h to FFFFh (Data)				
On	8x 01 04 15 02 FF	Display On/Off				
Off	8x 01 04 15 03 FF					
On/Off	8x 01 04 15 10 FF					
Title Set1	8x 01 04 73 1L 00 nn pp qq 00 00 00 00 00 00 FF	L: Line Number, nn: H-position pp: Color, qq: Blink				
Title Set2	8x 01 04 73 2L mm nn pp	L: Line Number,				
T:41- C-42		mnpqrstuvw: Setting of characters (1 to 10) L: Line Number.				
Title Set3	11	mnpqrstuvw: Setting of characters (11 to 20)				
Title Clear	8x 01 04 74 1p FF	Title Setting clear (p: 0h to Ah, F= all lines)				
On	8x 01 04 74 2p FF	Title display On/Off (p: 0h to Ah, F= all lines)				
Off	8x 01 04 74 3p FF					
On	8x 01 04 75 02 FF	Muting On/Off				
Off	8x 01 04 75 03 FF					
On/Off	8x 01 04 75 10 FF					
		mm: Mask Settings				
	Or Or Os Os FF	nn 00: Modify, 01: New				
		rr: W, ss: H				
SetMaskTable	8x 01 05 70 0p FF	p: Table (0h to 1h)				
Display	8x 01 04 77 pp pp pp pp FF	Mask Display On/Off				
SetMaskColor	8x 01 04 78 pp pp pp pp	pp pp pp pp: Mask Settings (0: Off, 1: On) pp pp pp pp: Mask Color Settings				
SetWaskColor		qq: Color Setting when 0 is selected				
	11	rr: Color Setting when 1 is selected				
SetPanTiltAngle	8x 01 04 79 0p 0p 0p	Pan/Tilt Angle Settings				
	0q 0q 0q FF	ppp: Pan qqq: Tilt				
SetPTZMask	8x 01 04 7B mm 0p 0p 0p	Pan/Tilt/Zoom Settings for Mask				
	0q 0q 0q 0r 0r 0r 0r FF	ppp: Pan, qqq: Tilt, rrrr: Zoom, mm: Mask Settings				
Non_InterlockMask	8x 01 04 6F mm	mm: Non_Interlock Mask Settings				
	0p 0p 0q 0q 0r 0r 0s 0s FF	pp: X, qq: Y, rr: W, ss: H				
	8x 01 04 7C 03 FF	Center Line Display Off				
CenterLineOn	8x 01 04 7C 04 FF	Center Line Display On				
	8x 01 04 22 0p 0q 0r 0s FF	pqrs: Camera ID (=0000h to FFFFh)				
On	8x 01 04 69 02 FF	Zoom Position data Continuous Output On/Off				
Off	8x 01 04 69 03 FF					
(Reply)	y0 07 04 69 0p 0p 0q 0q 0q 0q FF	pp: D-Zoom Position				
		* 00: When Zoom Mode is Combine				
	9 - 01 04 64 00 00 0 - 0 - EE	qqqq: Zoom Position				
-	8x 01 04 6A 00 00 0p 0p FF	pp: Interval Time [V cycle] 01h to FFh				
	1					
On	8x 01 04 16 02 FF	Focus Position data Continuous Output On/Off				
On Off	8x 01 04 16 02 FF 8x 01 04 16 03 FF	Focus Position data Continuous Output On/Off				
	Reset Set Recall Reset Set Recall Write On Off On/Off Title Set1 Title Set2 Title Clear On Off On/Off SetMaskTable Display SetMaskColor SetPanTiltAngle SetPTZMask Non_InterlockMask CenterLineOff On Off On	Reset 8x 01 04 3F 00 pp FF Set 8x 01 04 3F 01 pp FF Recall 8x 01 04 3F 02 pp FF Reset 8x 01 04 3F 00 7F FF Set 8x 01 04 3F 02 7F FF Write 8x 01 04 15 02 7F FF Write 8x 01 04 15 02 7F FF On 8x 01 04 15 02 FF Off 8x 01 04 15 03 FF On/Off 8x 01 04 15 10 FF Title Set1 8x 01 04 73 1L 00 nn pp qq 000 000 000 000 000 FF Title Set2 8x 01 04 73 2L mm nn pp qq rr ss tt uu vv wr FF Title Set3 8x 01 04 73 2L mm nn pp qq rr ss tt uu vv wr FF On 8x 01 04 74 3p FF Off 8x 01 04 75 02 FF Off 8x 01 04 75 03 FF On/Off 8x 01 04 75 03 FF On/Off 8x 01 04 75 00 pF SetMask 8x 01 04 77 0p pp pp pp FF SetMask 8x 01 04 77 0p FF Display 8x 01 04 77 0p FF SetMaskColor 8x 01 04 78 pp pp pp pp pp qq rr FF SetPanTiltAngle 8x 01 04 79 0p 0p 0p 0p 0q 0q 0q 0q 0r 0r 0r 0r FF Non_InterlockMask 8x 01 04 78 mm 0p				

Command List (6/7)

Command Set	Command	Command Packet	Comments				
CAM_FocusPosReply	_	8x 01 04 1A 00 00 0p 0p FF	pp: Interval Time [V cycle] 01h to FFh				
IntervalTimeSet							
CAM_RegisterValue	-	8x 01 04 24 mn 0p 0q FF	mn: Register No. (=00h to 7Fh)				
			pq: Register Value (=00h to FFh)				
CAM_ColorEnhance	Parameter Set	8x 01 04 20 mm 00 pp 40 40 ss 40 40 FF	mm: Threshold level				
			pp: Y fixed color for high-intensity				
			ss: Y fixed color for low-intensity				
			Each parameter setting 00h to 7Fh				
	On	8x 01 04 50 02 FF	Color Enhancement On/Off				
	Off	8x 01 04 50 03 FF					
CAM_ChromaSuppress	-	8x 01 04 5F 0p FF	p: Chroma Suppress setting level				
			00: Off				
			01h to 03h: On (3 levels).				
			Effect increases as the level number increases.				
CAM_ColorGain	Direct	8x 01 04 49 00 00 00 0p FF	p: Color Gain Setting 0h (60%) to Eh (200%)				
CAM_ColorHue	Direct	8x 01 04 4F 00 00 00 0p FF	p: Color Hue Setting 0h (-14 degrees) to Eh (+14 degrees)				
CAM_ExExpComp	Reset	8x 01 04 1F 0E 00 00 FF	Exposure compensation reset				
(Extended command)	Up	8x 01 04 1F 0E 02 pp FF	Exposure compensation up				
			pp: Step number				
			pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Down	8x 01 04 1F 0E 03 pp FF	Exposure compensation down				
			pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Direct	8x 01 04 1F 4E 00 00 0p 0q FF	Set the exposure compensation to the specified level				
			pq: Level				
			pq=00h to FFh				
CAM_ExAperture	Reset	8x 01 04 1F 02 00 00 FF	Aperture control reset				
(Extended command)	Up	8x 01 04 1F 02 02 pp FF	Aperture control up				
			pp: Step number				
	Deserv	0 01 04 1E 02 02 EE	pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Down	8x 01 04 1F 02 03 pp FF	Aperture control down pp: Step number				
			pp=00h to 7Fh (However, 00h is the same operation as 01h.)				
	Direct	8x 01 04 1F 42 00 00 0p 0q FF	Set the aperture control to the specified level				
			pq: Level				
			pq=00h to FFh				
CAM_ExAutoICR	Threshold	8x 01 04 1F 21 00 00 0p 0q FF	pq: ICR ON→OFF threshold level when Auto ICR pq=00h to FFh				
(Extended command)	(ON→OFF) On Level	8x 01 04 1F 21 01 00 0r 0s FF	pq -oon to FF pq : ICR OFF \rightarrow ON threshold level when Auto ICR				
	On Level	8X 01 04 11 21 01 00 01 05 11	pq=00h to 16h				
CAM_ExColorGain	Direct	8x 01 04 1F 49 00 00 0p 0q FF	Color Gain Setting				
(Extended command)			pq: Gain setting level				
			pq=00h (0%) to FFh (200%)				
CAM_ExColorHue	Direct	8x 01 04 1F 4F 00 00 0p 0q FF	Color Hue Setting pq: Phase setting level				
(Extended command)			pq=00h (-14 degrees) to FFh (14 degrees)				
CAM_HLC	Parameter Set	8x 01 04 14 0p 0q FF	p: HLC level (0: Off, 1: On) q: HLC mask level (0: Off, 1: On)				
CAM_ColorBar	Off	8x 01 7E 04 7D 00 FF	4: HLC mask level (0: 01, 1: 01)				
	On (Color bar 100%	8x 01 7E 04 7D 01 FF	-				
	8 colors)						
	On (Color bar 100%	8x 01 7E 04 7D 02 FF	-				
	7 colors)						
	On (Gray scale)	8x 01 7E 04 7D 03 FF					
	On (Gray scale)	δx 01 /E 04 /D 03 FF					

Command List (7/7)

Command Set	Command	Command Packet	Comments
CAM_ePT	On	8x 01 7E 06 00 02 FF	
	Off	8x 01 7E 06 00 03 FF	
	Absolute Position	8x 01 7E 06 20 00 00 0y 0y 0y 0y 0z	yyyy: Pan Position, zzzz: Tilt Position
		0z 0z 0z FF	*Supplementary explanation:
			Pan Position is specified in units of 6 pixels and Tilt
			Position is specified in units of 4.5 pixels (cut off after the
			decimal point)
CAM_MaintenanceMode	Step1	8x 01 04 00 0C FF	Used in maintenance mode
	Step2	8x 01 04 00 0D FF	
	Step3	8x 01 04 00 13 FF	
	Step4	8x 01 04 00 04 FF	1
	Updata	8x 01 04 00 20 FF]

Inquiry Command List (1/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_PowerInq	8x 09 04 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off (Standby)
CAM_ZoomPosInq	8x 09 04 47 FF	y0 50 0p 0q 0r 0s FF	pqrs: Zoom Position
CAM_DZoomModeInq	8x 09 04 06 FF	y0 50 02 FF	D-Zoom On
		y0 50 03 FF	D-Zoom Off
CAM_DZoomC/SModeInq	8x 09 04 36 FF	y0 50 00 FF	Combine Mode
		y0 50 01 FF	Separate Mode
CAM_DZoomPosInq	8x 09 04 46 FF	y0 50 00 00 0p 0q FF	pq: D-Zoom Position
CAM_FocusModeInq	8x 09 04 38 FF	y0 50 02 FF	Auto Focus
		y0 50 03 FF	Manual Focus
CAM_FocusPosInq	8x 09 04 48 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Position
CAM_FocusNearLimitInq	8x 09 04 28 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position
CAM_SpotFocusModeInq	8x 09 05 08 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotFocusPosInq	8x 09 05 68 FF	y0 50 0p 0q 0r 0s FF	pq: X, rs: Y
CAM_AFSensitivityInq	8x 09 04 58 FF	y0 50 02 FF	AF Sensitivity Normal
		y0 50 03 FF	AF Sensitivity Low
CAM_AFModeInq	8x 09 04 57 FF	y0 50 00 FF	Normal AF
		y0 50 01 FF	Interval AF
		y0 50 02 FF	Zoom Trigger AF
CAM_AFTimeSettingInq	8x 09 04 27 FF	y0 50 0p 0q 0r 0s FF	pq: Movement Time, rs: Interval
CAM_LowLightBasis	8x 09 05 39 FF	y0 50 02 FF	On
BrightnessInq		y0 50 03 FF	Off
CAM_LowLightBasis	8x 09 05 49 FF	y0 50 0p FF	p: Position
BrightnessPosInq CAM_IRCorrectionInq	8x 09 04 11 FF	y0 50 00 FF	Standard
		y0 50 01 FF	IR Light
CAM_WBModeInq	8x 09 04 35 FF	y0 50 00 FF	Auto
		y0 50 01 FF	Indoor
		y0 50 02 FF	Outdoor
		y0 50 03 FF	One Push WB
		y0 50 04 FF	ATW
		y0 50 05 FF	Manual
		y0 50 06 FF	Outdoor Auto
		y0 50 07 FF	Sodium Lamp Auto
		y0 50 08 FF	Sodium Lamp
		y0 50 09 FF	Sodium Lamp Outdoor Auto
CAM_RGainInq	8x 09 04 43 FF	y0 50 00 00 0p 0q FF	pq: R Gain
CAM_BGainInq	8x 09 04 44 FF	y0 50 00 00 0p 0q FF	pq: B Gain
CAM_AEModeInq	8x 09 04 39 FF	y0 50 00 FF	Full Auto
		y0 50 03 FF	Manual
		y0 50 0A FF	Shutter Priority
		y0 50 0B FF	Iris Priority
		y0 50 0D FF	Bright
CAM_ShutterPosInq	8x 09 04 4A FF	y0 50 00 00 0p 0q FF	pq: Shutter Position
CAM_MaxShutterInq	8x 09 05 2A 00 FF	y0 50 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutterInq	8x 09 05 2A 01 FF	y0 50 0p 0q FF	pq: Low-speed shutter limit
CAM_SlowShutterInq	8x 09 04 5A FF	y0 50 02 FF	On
*		y0 50 03 FF	Off
CAM_SlowShutterLimitInq	8x 09 05 5A FF	y0 50 0p 0q FF	pq: Slow Shutter Limit

Inquiry Command List (2/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_IrisPosInq	8x 09 04 4B FF	y0 50 00 00 0p 0q FF	pq: Iris Position
CAM_GainPosInq	8x 09 04 4C FF	y0 50 00 00 0p 0q FF	pq: Gain Position
CAM_GainLimitInq	8x 09 04 2C FF	y0 50 0q FF	p: Gain Limit
CAM_GainPointInq	8x 09 05 4C FF	y0 50 0p 0q FF	pq: Gain Point
Gain Point On/Off Inq	8x 09 05 0C FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_BrightPosInq	8x 09 04 4D FF	y0 50 00 00 0p 0q FF	pq: Bright Position
CAM_ExpCompModeInq	8x 09 04 3E FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ExpCompPosInq	8x 09 04 4E FF	y0 50 00 00 0p 0q FF	pq: ExpComp Position
CAM_BackLightModeInq	8x 09 04 33 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotAEPosInq	8x 09 04 29 FF	y0 50 0p 0q 0r 0s FF	pq: X Position, rs: Y Position
CAM_SpotAEModeInq	8x 09 04 59 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_VEModeInq	8x 09 04 3D FF	y0 50 03 FF	Off
		y0 50 06 FF	VE On
CAM_VEParameterInq	8x 09 04 2D FF	y0 50 00 0q 0r 0s 0t 0u 00 00 FF	q: Display brightness level (0: Dark to 6: Bright)r: Brightness compensation selection (0: Very dark,1: Dark, 2: Standard, 3: Bright)s: Compensation level (00h: Low, 01h: Mid, 02h: High)tu: Always 0
CAM_AEResponseInq	8x 09 04 5D FF	y0 50 pp FF	pp: 01h to 30h
CAM_DefogInq	8x 09 04 37 FF	y0 50 02 0p FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)
		y0 50 03 00 FF	Defog Off
CAM_ApertureInq	8x 09 04 42 FF	y0 50 00 00 0p 0q FF	pq: Aperture Gain
CAM_ApertureModeInq	8x 09 05 42 01 FF	x0 50 0p FF	p: Auto (0), Manual (1)
CAM_ApertureBandwidthInq	8x 09 05 42 02 FF	x0 50 0p FF	p: Bandwidth
CAM_ApertureCrispeningInq	8x 09 05 42 03 FF	x0 50 0p FF	p: Crispening
CAM_ApertureH/VBalance	8x 09 05 42 04 FF	x0 50 0p FF	p: H/V Balance
CAM_ApertureB/WBalance	8x 09 05 42 05 FF	x0 50 0p FF	p: B/W Balance
CAM_ApertureLimitInq	8x 09 05 42 06 FF	x0 50 0p FF	p: Limit
CAM_ ApertureHighLightDetailInq	8x 09 05 42 07 FF	x0 50 0p FF	p: High light detail
CAM_ApertureSuperLowInq	8x 09 05 42 08 FF	x0 50 0p FF	p: Super low emphasis
CAM_HRModeInq	8x 09 04 52 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_NRInq	8x 09 04 53 FF	y0 50 0p FF	Noise Reduction p: 00h to 05h, 7Fh
CAM_NR2D3DInq	8x 09 05 53 FF	y0 50 0p 0q FF	p: 2D NR Level, q: 3D NR Level
CAM_StabilizerModeInq	8x 09 04 34 FF	y0 05 02 FF	On
		y0 05 03 FF	Off
CAM_GammaInq	8x 09 04 5B FF	y0 50 0p FF	Gamma p: 00h, 01h
CAM_GammaPatternInq	8x 09 05 5B FF	y0 50 0p 0q 0r FF	pqr: Selection pattern
CAM_GammaOffsetInq	8x 09 04 1E FF	y0 50 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus)
			tu: Offset s=0 (00h to 40h)
CAM HighSongitivityIng	9x 00 04 55 55	v0.50.02 EE	Offset s=1 (00h to 10h)
CAM_HighSensitivityInq	8x 09 04 5E FF	y0 50 02 FF	On Off
		y0 50 03 FF	Off

Inquiry Command List (3/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_LR_ReverseModeInq	8x 09 04 61 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_FreezeModeInq	8x 09 04 62 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_PictureEffectModeInq	8x 09 04 63 FF	y0 50 00 FF	Off
		y0 50 04 FF	Black & White
CAM_PictureFlipModeInq	8x 09 04 66 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ICRModeInq	8x 09 04 01 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_AutoICRModeInq	8x 09 04 51 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_AutoICRThresholdInq	8x 09 04 21 FF	y0 50 00 00 0p 0q FF	pq: ICR On \rightarrow Off Threshold Level
CAM_AutoICRAlarmReplyInq	8x 09 04 31 FF	y0 50 02 FF	On
- 17 1		y0 50 03 FF	Off
CAM_AutoICRAlarmReply	(Reply)	y0 07 04 31 0p FF	p: 2=Off \rightarrow On, 3=On \rightarrow Off
CAM_MemoryInq	8x 09 04 3F FF	y0 50 pp FF	p: Memory number recalled last
CAM_MemSaveInq	8x 09 04 23 0X FF	y0 50 0p 0q 0r 0s FF	X: 00h to 07h (Address)
1		/····	pqrs: 0000h to FFFFh (Data)
CAM_DisplayModeInq	8x 09 04 15 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_MuteModeInq	8x 09 04 75 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SetMaskTableInq	8x 09 05 70 FF	y0 50 0m FF	m: Table
CAM_PrivacyDisplayInq	8x 09 04 77 FF	y0 50 pp pp pp pF	pp pp pp pp: Mask Display (0: Off, 1: On)
CAM_PrivacyPanTiltInq	8x 09 04 79 FF	y0 50 0p 0p 0p 0q 0q 0q FF	ppp: Pan
			qqq: Tilt
CAM_PrivacyPTZInq	8x 09 04 7B mm FF	y0 50 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r	
		FF	ppp: Pan
			qqq: Tilt rrrr: Zoom
CAM_PrivacyMonitorInq	8x 09 04 6F FF	y0 50 pp pp pp pp FF	pp pp pp pp: Mask is displayed now.
CAM_IDInq	8x 09 04 22 FF	y0 50 0p 0q 0r 0s FF	pqrs: Camera ID
CAM_VersionInq	8x 09 00 02 FF	y0 50 00 20	mnpq: Model Code (04xx)
orming (ensembled)		mn pq rs tu vw FF	rstu: ROM version
			vw: Socket Number (=02)
CAM_ContinuousZoomPos	8x 09 04 69 FF	y0 50 02 FF	On
ReplyModeInq		y0 50 03 FF	Off
CAM_ZoomPosReply	8x 09 04 6A FF	y0 50 00 00 0p 0p FF	pp: Interval Time
IntervalTimeInq			
CAM_Continuous	8x 09 04 16 FF	y0 50 02 FF	On
FocusPosReplyModeInq		y0 50 03 FF	Off
CAM_ExAutoICROnLevelInq	8x 09 04 1F 21 01 FF	y0 50 00 00 0p 0q FF	pq:Auto ICR Off/On threshold at ICR pq=00h to 1Ch
CAM_MinShutterInq	8x 09 04 12 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_MinShutterLimitInq	8x 09 04 13 FF	y0 50 00 00 0p 0q FF	pq: MinShutter Position
CAM_HLCInq	8x 09 04 14 FF	y0 50 0p 0q FF	p: HLC level (0: OFF, 1: low, 2: mid, 3: high) q: HLC mask level (0: OFF, 1 to F: level low to high)
CAM_RegisterValueInq	8x 09 04 24 pp FF	y0 50 0q 0q FF	pp: Register No.
CAM_ContinuousZoomPos ReplyModeInq	8x 09 04 69 FF	y0 50 0p FF	p: 2=On, 3=Off

Inquiry Command List (4/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_ContinuousFocusPos ReplyModeInq	8x 09 04 16 FF	y0 50 0p FF	p: 2=On, 3=Off
CAM_FocusPosReplyInterval TimeInq	8x 09 04 1A FF	y0 50 00 00 0p 0p FF	pp: Interval Time
(Reply)	-	y0 07 04 16 00 00 0p 0p 0p 0p FF	pppp: Focus Position
CAM_ColorBarInq	8x 09 7E 04 7D FF	y0 50 00 FF	OFF
		y0 50 01 FF	Color bar 100% 8 colors
		y0 50 02 FF	Color bar 100% 7 colors
		y0 50 03 FF	Grayscale
CAM_ePTModeInq	8x 09 7E 06 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ePTPositionInq	8x 09 7E 06 20 FF	y0 50 00 00 0p 0p 0p 0p 0t 0t 0t 0t	pppp: Pan Position
		FF	tttt: Tilt Position
CAM_TempInq	8x 09 04 68 FF	y0 50 00 00 0p 0p FF	pp: Lens Temperature

Block Inquiry Command List

Lens Control System Inquiry CommandsCommand Packet 8x 09 7E 7E 00 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
•	7			7	0	-	7	0
	6			6	0		6	0
	5	Destination Address		5	0		5	0
	4			4	0		4	0
0	3		6	3	-	12	3	0
	2			2			2	0
		Source Address		1	Focus Near Limit (H)		1	0
	0			0			0	0
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	Digital Zoom (H)
	5	0		5	0		5	DZoomMode 0: Combine
	4	1		4	0			1: Separate
1	3	0	7	3			4	0: Normal 1: Interval
	2	0		2		13	3	2: Zoom Trigger
	1	0		1	Focus Near Limit (L)		2	AF Sensitivity 0: Low
	0	0		0				1: Normal
	7	0		7	0		1	Digital Zoom 1: On 0: Off
	6	0		6	0		0	Focus Mode 0: Manual 1: Auto
	5	0		5	0		7	0
	4	0		4	0		6	0
2	3		8	3			5	0
	2	Zoom Position (HH)		2	Earne Davidian (IIII)		4	0
	1			1	Focus Position (HH)		3	Low Contrast Detection 1: Yes
	0			0				0: No
	7	0		7	0	14	2	Camera Memory Recall
	6	0		6	0			1: Executing 0: Stopped
	5	0		5	0		1	Focus Command 1: Executing
3	4	0	9	4	0			0: Stopped
5	3			3			0	Zoom Command 1: Executing
	2	Zoom Position (HL)		2	Focus Position (HL)			0: Stopped
	1			1			7	1 Terminator (FFh)
	0			0			6	1
	7	0		7	0		5	1
	6	0		6	0	15	4	1
	5	0		5	0		3	1
4	4	0	10	4	0		2	1
-	3			3			1	1
	2	Zoom Position (LH)		2	Focus Position (LH)		0	1
	1	× /		1				
	0			0				
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
5	4	0	11	4	0			
	3			3				
	2	Zoom Position (LL)		2	Focus Position (LL)			
	1			1				
	0			0				

Camera Control System Inquiry CommandsCommand Packet 8x 09 7E 7E 01 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6			6	0		6	0
	5	Destination Address		5	0		5	0
0	4			4	0		4	0
0	3		6	3		12	3	
	2			2			2	
	1	Source Address		1	WB Mode		1	Gain Position
	0			0			0	
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
_	4	1		4	0		4	
1	3	0	7	3		13	3	
	2	0		2			2	Bright Position
	1	0		1	Aperture Gain		1	
	0	0		0			0	
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
	4	0	8	4	0		4	0
2	3			3		14	3	
	2			2			2	
	1	R Gain (H)		1	Exposure Mode		1	Exposure Comp. Position
	0			0			0	
	7	0		7	0		7	1 Terminator (FFh)
	6	0		6	0		6	1
	5	0		5	High Resolution 1: On 0: Off		5	1
	4	0		4	VE 1: On 0: Off		4	1
3	3		9	3	Spot AE 1: On 0: Off	15	3	1
	2			2	Backlight 1: On 0: Off		2	1
	1	R Gain (L)		1	Exposure Comp. 1: On 0: Off		1	1
	0			0	Slow Shutter 1: On 0: Off		0	1
	7	0		7	0		1	
	6	0		6	0			
	5	0		5	0	1		
	4	0		4		1		
4	3		10	3				
	2			2	Shutter Position			
	1	B Gain (H)		1				
	0			0				
	7	0		7	0	1		
	6	0		6	0	1		
	5	0		5	0	1		
	4	0	11	4		1		
5	3			3				
	2			2	Iris Position			
	1	B Gain (L)		1				
			1	1	1	1		

Other Inquiry CommandsCommand Packet 8x 09 7E 7E 02 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6			6	0		6	0
5	Destination Address		5	0		5	0	
0	4			4	0		4	Memory 1: Provided 0: Not
0	3		6	3	0			provided
	2	C 411		2	0		3	0
	1	Source Address		1	0	12	2	ICR 1: Provided 0: Not
	0			0	0			provided
	7	0 Completion Message (50h)		7	0		1	Stabilizer 1: Provided 0: Not provided
	6	1		6	0		0	System 1: 1/50, 1/25 0: 1/59.94,
	5	0		5	0			1/29.97
1	4	1	7	4	0		7	0
	3	0		3	0		6	0
	2	0		2	0		5	0
	1	0		1	0		4	0
	0	0		0	0	13	3	0
	7	0		7	0		2	0
	6	0		6	0		1	0
	5	0		5	0		0	0
2	4	0	0	4	0		7	0
2	3	Auto ICR Alarm (1: On, 0: Off)	8	3			6	0
	2	Auto ICR 1: On 0: Off		2	Camera ID (HH)		5	0
	1	0		1			4	0
	0	Power 1: On 0: Off		0		14	3	0
	7	0		7	0		2	0
	6	Stabilizer 1: On 0: Off		6	0		1	0
	5	0		5	0		0	0
2	4	ICR 1: On 0: Off		4	0		7	1 Terminator (FFh)
3	3	Freeze 1: On 0: Off	9	3			6	1
	2	LR Reverse 1: On 0: Off		2			5	1
	1	0		1	Camera ID (HL)		4	1
	0	0		0		15	3	1
	7	0		7	0		2	1
	6	0		6	0		1	1
	5	Privacy Zone 1: On 0: Off		5	0		0	1
4	4	Mute 1: On 0: Off	10	4	0			
4	3	Title Display 1: On 0: Off		3				
	2	Display 1: On 0: Off		2	Camera ID (LH)			
	1	0		1				
	0	0		0				
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
F	4	0	11	4	0			
5	3		11	3				
	2	Distance Different M. 1		2	Comercia ID (11)			
	1	Picture Effect Mode		1	Camera ID (LL)			
	0			0				

Extended Function1 Query CommandCommand Packet 8x 09 7E 7E 03 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	Destination Address		6	0		6	
	5	Destination Address		5	0		5	Color Gain (0h (60%) to
	4			4	0		4	Eh (200%))
0	3		6	3			3	
	2			2		11	2	Advanced Privacy
	1	Source Address		1	AF Interval Time (H)			(1: Provided, 0: Not provided)
	0			0			1	Reserved
	7	0 Completion Message (50h)		7	0		0	E-Flip (1: Provided, 0: Not provided)
	6	1		6	0		7	0
	5	0		5	0		6	0
1	4	1	7	4	0		5	
	3	0		3			4	
	2	0		2		12	3	
	1	0		1	AF Interval Time (L)		2	AE Response
	0	0		0			1	
	7	0		7	0		0	
	6	0		6	0		7	0 Gamma
	5	0		5	0		6	
	4	0		4	0		5	
2	3		8	3	U U		4	
				2		13	3	High Sensitivity mode
		Digital Zoom Position (H)		1	Spot AE Position (X)	15	5	(1: On, 0: Off)
	0			0			2	
	7	0		7	0		1	NR Level
	6	0		6	0		0	INK Level
	5	0		5	0		7	0
		0			0			0
3	4	0	9	4	0		6	Character Gamman
	3			3			5	Chroma Suppress
	2	Digital Zoom Position (L)		2	Spot AE Position (Y)	14	4	
	1			1			3	
	0			0	<u></u>		2	Gain Limit
	7	0		7	0		1	
	6	0		6	0		0	
	5	0		5	0		7	1 Terminator (FFh)
4	4	0	10	4	0		6	1
	3			3	0		5	1
	2	AF Activation Time (H)		2	Reserved	15	4	1
	1			1	0		3	1
	0			0	E-Flip (1: On, 0: Off)		2	1
	7	0					1	1
	6	0					0	1
	5	0						
5	4	0						
-	3							
	2	AF Activation Time (L)						
	1							

Extended Function2 Query CommandCommand Packet 8x 09 7E 7E 04 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
0	6	Destination Address		6	0		6	0
	5			5	0		5	0
	4		6	4	0	11	4	0
0	3			3	0	11	3	0
	2	Source Address		2	0		2	0
	1	Source Address		1	Compensation level		1	0
	0			0	0: Low 1: Mid 2: High		0	0
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
1	4	1	7	4	0	12	4	0
1	3	0		3	0	12	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0		0	Defog 0: Off 1: On		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0	8	5	0	13	5	0
	4	0		4	0		4	0
	3	0		3	0		3	0
	2	0		2	0		2	0
	1	VE		1	Defog Level		1	0
	0	0: Off 2: VE On		0	0: mid 1: low 2: mid 3: high		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0	1	5	0		5	0
	4	0	1	4	0		4	0
3	3	0	- 9	3	0	14	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0	┨╞────	0	0		0	0
	7	0		7	0		7	1 Terminator (FFh)
	6	0		6	0		6	1
	5	0		5	0		5	1
4	4	0	10	4	0	15	4	1
1	3	0		3	0	1.5	3	1
	2	Display brightness level setting		2	0		2	1
	1	0: Dark to 6: Bright		1	0		1	1
	0			0	0		0	1
	7	0	1			L		
	6	0	1					
	5	0	1					
\vdash	4	0	1					
	-							
5	3	0	1					

0: Very dark 1: Dark 2: Standard 3: Bright

Brightness compensation selection

1

0

Extended Function3 Query CommandCommand Packet 8x 09 7E 7E 05 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments		
	7			7	0]	7	0		
	6	Destination Address		6]	6			
	5			5			5			
0	4		6	4		11	4			
	3		0	3	Reserved		3	Reserved		
	2	Source Address		2			2			
	1	Source Address		1			1			
	0			0			0			
	7	0 Completion Message (50h)		7	0		7	0		
	6	1		6			6			
	5	0		5			5			
1	4	1	7	4		12	4			
-	3	0		3	Reserved		3	Reserved		
	2	0		2			2			
	1	0		1			1			
	0	0		0		┨┝────	0			
	7	0		7	0		7	0		
	6	0		6			6			
	5	0		5			5			
2	4	0	8	4		13	4			
	3			3	Reserved		3	Reserved		
	2	Color Hue		2			2			
	1	(0h(- 14 degrees) to Eh(+ 14 degrees))		1			1			
	0			0			0			
	7	0		7	0		7	0		
	6			6			6			
	5		9 3 2 1	9		5			5	
2	4					0	4		14	4
3	3	Reserved			3	Reserved	14	3	Reserved	
	2			2			2			
	1			1			1			
				0						
	0						0			
	7	0		7	0		76	1 Terminator (FFh)		
	6			6			5	1 1		
	5					4	1			
4	4		10		15	3	1			
	2	Reserved		3 2	Reserved		2	1		
	1			1			1	1		
	0			0			0	1		
	7	0								
	6									
	5									
5	4									
č	3	Reserved								
	2									
	1									
	0									

VISCA Command Setting Values

Exposure control (1/3)

		59.94/29.97 mode	50/25 mode	23.98 mode
Shutter Speed/	21	1/10000	1/10000	1/10000
Slow Shutter Limit	20	1/6000	1/6000	1/4800
	1F	1/4000	1/3500	1/2400
	1E	1/3000	1/2500	1/1200
	1E	1/2000	1/1750	1/576
	1C	1/1500	1/1250	1/400
	1B	1/1000	1/1000	1/288
	1A	1/725	1/600	1/200
	19	1/500	1/425	1/192
	18	1/350	1/300	1/144
	17	1/250	1/215	1/120
	16	1/180	1/150	1/100
	15	1/125	1/120	1/96
	14	1/100	1/100	1/60
	13	1/90	1/60	1/50
	12	1/60	1/50	1/48
	11	1/50	1/30	1/40
	10	1/30	1/25	1/25
	0F	1/20	1/20	1/24
	0E	1/15	1/15	1/20
	0D	1/10	1/12	1/12
	0C	1/8	1/8	1/8
	0B	1/6	1/6	1/6
	0A	1/4	1/4	1/4
	09	1/3	1/3	1/3
	08	1/2	1/2	1/2
	07	2/3	2/3	2/3
	06	1/1	1/1	1/1

		59.94/29.97 mode	50/25 mode	23.98 mode
High speed	21	1/10000	1/10000	1/10000
Shutter Limit	20	1/6000	1/6000	1/4800
	1F	1/4000	1/3500	1/2400
	1E	1/3000	1/2500	1/1200
	1D	1/2000	1/1750	1/576
	1C	1/1500	1/1250	1/400
	1B	1/1000	1/1000	1/288
	1A	1/725	1/600	1/200
	19	1/500	1/425	1/192
	18	1/350	1/300	1/144
	17	1/250	1/215	1/120
	16	1/180	1/150	1/100
	15	1/125	1/120	1/96
	14	1/100	1/100	1/60
	13	1/90	1/60	1/50
	12	1/60	1/50	1/48
	11	1/50	1/30	1/40
	10	1/30	1/25	1/25
	0F	-	-	1/24
Slow Shutter	11	1/50	1/30	1/40
Limit	10	1/30	1/25	1/25
	0F	1/20	1/20	1/24
	0E	1/15	1/15	1/20
	0D	1/10	1/12	1/12
	0C	1/8	1/8	1/8
	0B	1/6	1/6	1/6
	0A	1/4	1/4	1/4
	09	1/3	1/3	1/3
	08	1/2	1/2	1/2
	07	2/3	2/3	2/3
	06	1/1	1/1	1/1

Exposure control (2/3)

Iris	19	F2.0
	18	F2.2
	17	F2.4
	16	F2.6
	15	F2.8
	14	F3.1
	13	F3.4
	12	F3.7
	11	F4.4
	10	F4.0
	0F	F4.8
	0E	F5.2
	0D	F5.6
	0C	F6.2
	0B	F6.8
	0A	F7.3
	09	F6.8
	08	F8
	07	F9.6
	06	F10
	05	F11
	00	CLOSE

		High Sensi	tivity mode
		Off	On
Gain Limit	D	36 dB	48 dB
	С	33 dB	45 dB
	В	30 dB	42 dB
	А	27 dB	39 dB
	9	24 dB	36 dB
	8	21 dB	33 dB
	7	18 dB	30 dB
	6	15 dB	27 dB
	5	12 dB	24 dB
	4	9 dB	21 dB

Gain	11	48 dB
	10	45 dB
	0F	42 dB
	0E	39 dB
	0D	36 dB
	0C	33 dB
	0B	30 dB
	0A	27 dB
	09	24 dB
	08	21 dB
	07	18 dB
	06	15 dB
	05	12 dB
	04	9 dB
	03	6 dB
	02	3 dB
	01	0 dB

0D to 10 can be set only when the high-sensitivity mode is ON.

Exposure control (3/3)

		Iris	Gain
Bright	29	F2.0	48 dB
	28	F2.0	45 dB
	27	F2.0	42 dB
	26	F2.0	39 dB
	25	F2.0	36 dB
	24	F2.0	33 dB
	23	F2.0	30 dB
	22	F2.0	27 dB
	21	F2.0	24 dB
	20	F2.0	21 dB
	1F	F2.0	18 dB
	1E	F2.0	15 dB
	1D	F2.0	12 dB
	1C	F2.0	9 dB
	1B	F2.0	6 dB
	1A	F2.0	3 dB
	19	F2.0	0 dB
	18	F2.2	0 dB
	17	F2.4	0 dB
	16	F2.6	0 dB
	15	F2.8	0 dB
	14	F3.1	0 dB
	13	F3.4	0 dB
	12	F3.7	0 dB
	11	F4.0	0 dB
	10	F4.4	0 dB
	0F	F4.4 F4.8	0 dB
	0E 0D	F5.2 F5.6	0 dB 0 dB
	0C	F6.2	0 dB
	0B	F6.8	0 dB
	0A	F7.3	0 dB
	09	F8.0	0 dB
	08	F8.7	0 dB
	07	F9.6	0 dB
	06	F10	0 dB
	05	F11	0 dB
	00	CLOSE	0 dB

Exposure Comp.	0E	+7	+10.5 dB
	0D	+6	+9 dB
	0C	+5	+7.5 dB
	0B	+4	+6 dB
	0A	+3	+4.5 dB
	09	+2	+3 dB
	08	+1	+1.5 dB
	07	0	0 dB
	06	-1	-1.5 dB
	05	-2	-3 dB
	04	-3	-4.5 dB
	03	-4	-6 dB
	02	-5	-7.5 dB
	01	-6	-9 dB
	00	-7	-10.5 dB

Zoom Ratio and Zoom Position (for reference)

Optical Zoom Ratio	Optical Zoom Position Data
1×	0000
2×	0DC1
3×	186C
4×	2015
5×	2594
6×	29B7
7×	2CFB
8×	2FB0
9×	320C
10×	342D
11×	3608
12×	37AA
13×	391C
14×	3A66
15×	3B90
16×	3C9C
17×	3D91
18×	3E72
19×	3F40
20×	4000

1D to 20 can be set only when the high-sensitivity mode is ON.

Digital Zoom Combine mode

Digital Zoom Ratio	Digital Zoom Position Data
1×	4000
2×	6000
3×	6AAB
4×	7000
5×	7334
6×	7556
7×	76DC
8×	7800
9×	78E4
10×	799A
11×	7A2F
12×	7AC0

Digital Zoom Separate mode

Digital Zoom Ratio	Digital Zoom Position Data
1×	00
2×	80
3×	AA
4×	C0
5×	CC
6×	D5
7×	DB
8×	E0
9×	E3
10×	E6
11×	E8
12×	EB

Lens control

	0000 to 4000 to 7AC0
Zoom Position	wide end Optical Digital
	tele end tele end
Focus Position	1000 to F000
1 ocus 1 osition	Far end Near end
	1000: Over Inf
	2000: 10 m
	3000: 5 m
	4000: 3.3 m
Focus Near	5000: 2.5 m
	6000: 2 m As the distance on the left
	7000: 1.7 m will differ due to temperature
Limit	8000: 1.5 m characteristics, etc., use as
	9000: 1 m approximate values.
	A000: 50 cm *The lower 1 byte is fixed at 00
	B000: 30 cm
	(initial setting)
	C000: 15 cm
	D000: 6 cm
	E000: 1 cm

wide/tele Limit Setting

wide/tele Limit	wide Limit		tele Lir	nit
	Zoom	Zoom	Zoom	Zoom
Setting Value	Position	Ratio	Position	Ratio
00	0000	1.00	4000	20.00
10	0170	1.09	3E8F	18.14
20	02E0	1.18	3D1F	16.53
30	0450	1.28	3BAF	15.12
40	05C0	1.38	3A3F	13.89
50	0730	1.47	38CF	12.80
60	08A1	1.58	375E	11.83
70	0A11	1.69	35EE	10.96
80	0B81	1.81	347E	10.18
90	0CF1	1.94	32F7	9.44
A0	0E61	2.07	319E	8.83
B0	0FD1	2.19	302E	8.22
C0	1142	2.32	2EBD	7.65
D0	12B2	2.44	2D4D	7.13
E0	1422	2.58	2BDD	6.66
F0	1592	2.72	2A6D	6.22
FF	16EB	2.85	2914	5.85

Temperature Reading Conversion Value (Reference Value)

Reading Value pq (hex)	Temperature Conversion Value (°C)
FB	-8 to -2
00	-3 to +3
0A	7 to 13
14	17 to 23
1E	27 to 33
28	37 to 43
32	47 to 53
3C	57 to 63

Register Setting

The register settings are enabled when the power is turned off and then back on again. After turning the power back on again, verify that the mode settings have been changed.

	Register No.	Value	
VISCA	00	00	9600 bps
Baud Rate		(Initial Setting)	
		01	19200 bps
		02	38400 bps
		03	57600 bps
		04	115200 bps
Switching	01	00	VISCA
VISCA/		(Initial	
USB_PTP		Setting: 00)	
		01	USB_PTP
Digital	60	00	YUV
Output		(Initial Setting)	
		01	RGB

	Register No.	Value	
Monitoring	72	1D	System: QFHD
Mode		(Initial Setting)	(3840 × 2160) 29.97p
			Output: 3840 × 2160 29.97p
			1920 × 1080 29.974p
			When electronic pan/tilt is
			ON.
		1E	System: QFHD
			(3840 × 2160) 25p
			Output: 3840 × 2160 25p
			1920 × 1080 25p
			When electronic pan/tilt is
			ON.
		20	System: QFHD
			(3840 × 2160) 23.98p
			Output: 3840 × 2160 23.98p
			1920×1080 50p
			When electronic pan/tilt is
			ON.
		13	System: FHD (1920 × 1080)
			59.94p
			Output: 1920 × 1080 59.94p
		14	System: FHD (1920 × 1080)
			50p
			Output: 1920 × 1080 50p
		01	System: FHD (1920 × 1080)
			59.94i
			Output: 1920 × 1080 59.94i
		04	System: FHD (1920 × 1080)
			50i
			Output: 1920 × 1080 50i
		06	System: FHD (1920 × 1080)
			29.97p
			Output: 1920 × 1080 59.94p
			(2-2)
		08	System: FHD (1920 × 1080)
			25p
			Output: 1920 × 1080 50p (2-2)
		1F	System: FHD (1280 × 720)
			23.98p
			Output: 1280 × 720 23.98p
		09	System: HD (1280 × 720)
			59.94p
			Output: 1280 × 720 59.94p
		0C	System: HD (1280 × 720) 50p
			Output: 1280 × 720 50p
		1B	System: SD (720 × 480) 59.94p
			Output: 720 × 480 59.94p
		1C	System: SD (720 × 576) 50p
			Output: 720 × 576 50p

The frame rate of system in the monitoring mode is the screen update interval.

	Register No.	Value	
Low Delay	75	00	Normal Mode
Mode		01	Low Delay Mode
Zoom Limit	50	00-FF	Wide Limit
		(Initial Setting: 00)	(0: Disabled)
	51	00-FF	Tele Limit
		(Initial Setting: 00)	(0: Disabled)
D-Zoom Max	52	00-EB	Max. digital
		(Initial Setting: EB)	zoom ratio =
			256 ÷ (256-Value)
"StableZoom"	53	00	Off
		(Initial Setting: 00)	
		01	On
APR	56	00	On start-up APR
		(Initial Setting: 00)	OFF
		01	On start-up APR
			ON
FocusOffset	55	00-FF	00: None to
@DomeCover		(Initial Setting: 00)	FF: Max.
Extended	5F	00	0FF
Mode		bit: 0 Exposure com	pensation
		Extended 256 levels	On/Off
		bit: 1 Aperture Exte	nded 256 levels
		On/Off	
		bit: 2 Color Gain/H	ue Extended 256
		levels On/Off	
		bit: 3 Auto ICR Off \rightarrow On setting	
		enable On/Off	
		*For all of bit, 1 is to	activate, 0 is Off

Others

AF Active Time ¹⁾	00	to	FF
AF Interval Time ¹⁾	00	to	FF
Spot AE X position	00	to	0F
Spot AE Y position	00	to	0F
R Gain	00	to	FF
B Gain	00	to	FF
Aperture Control Level	00	to	0F
AE Response	01	to	30
AutoICR On \rightarrow Off Threshold Level	00	to	FF
Chroma Suppress setting level	00	to	03
Color Gain setting level	00	to	0E
Color Hue setting level	00	to	0E
Color Enhancement threshold level	00	to	7F
Color Enhancement Y fixed color	00	to	7F

¹⁾ Unit: One second

USB commands for firmware update

Basic specifications of commands and response

• Communication is performed in units of packets.

- The packet consists of a header (32 bytes) and body (from 0 byte).
- Two types of packets in a command and response are defined as described below.
 - Command Data transfer of a host to this unit
 - Response Data transfer of this unit to a host
 - One response packet is necessarily returned to one command packet.
 - *However, there is no response in a specific command.
- Byte array is based on a little-endian format.
- Description of notation
- Notation of type
- uint: Unsigned integer (Does not depend on the data length.)

Binary: Binary data string

Packet structure

The packet consists of a fixed-length (32-byte) header and size-variable body.

The maximum packet size is prescribed for each command or during communication parameter setting.

Data array	Size [Byte]	Туре
Packet{		
Packet Header	32	Packet Header
Body	n	Binary
}		

Packet Header (Common in both a command and response)

Data array	Size [Byte]	Туре
Packet Header{		
BodySize	4	uint
Protocol Version	2	uint
Command ID	2	uint
Response ID	2	uint
Sequence No.	2	uint
reserved	4	uint
reserved	4	uint
reserved	4	uint
reserved	8	uint
}		

Meaning

Body Size

This is the size of a body following a packet header. (The size of a packet header is not contained.)

Protocol Version

This is the version of a communication protocol. Fixed to 0x0100.

(The host sets the protocol version contained in firmware data.)

C

Command ID	
Command packet:	Sets the command to be executed.
Response packet:	The same value as the corresponding command packet is set.
Response ID	
Command packet:	Fixed to 0x0000.
Response packet:	ID indicating the processing result of the corresponding command
For more details, re	efer to the specifications for each
command. (See pag	ges 58 to 62.)
Sequence No.	
Command packet:	Sequence number unique in all commands
	Returned to 1 when an overflow occurs in the range of 1 to 65536.
Response packet:	Returns the sequence number of the corresponding command as it is.
	An error does not especially occur even when the value of a

sequence number is skipped.

Body

Data used as each command and response parameter is stored.

The body varies depending on each command and response.

ID list

Command ID	Definition of ID	Outline description
/*Initial communicatio	n*/	
0x0001	CMD_INIT	Initializes communication.
/*Judgment of rush cor	nditions*/	
0x0010	CMD_CHK_GUARD	Starts the judgment of rush conditions.
/*Inquiry of firmware v	//rersion*/	
0x0020	CMD_QUERY_VERSION	Inquires the version of firmware.
/*Start mode switching	request*/	
0x0030	CMD_SWITCH_MODE	Executes the switching to a firmware update mode.
/*Firmware rewrite*/		
0x0040	CMD_WRITE_FIRM	Transfers firmware data and writes it.
/*Completion check no	tification of rewrite processing*/	
0x0100	CMD_COMPLETE	Notifies the completion check of firmware update.
/*Acquisition of firmwa	are update processing status in this unit*/	
0x0200	CMD_GET_STATE	Acquires the firmware update processing status.

Deemen and ID	Definition of ID	Outline description (The detailed meaning varies depending or	
Response ID (STAT_ is also the same.)		each command.)	
/*Normal system*/			
0x0001	ERR_OK	Normal termination	
0x0002	ERR_BUSY	Processing in progress	
/*Communication pro	tocol error*/		
0x0100	ERR_PROV	Difference in protocol version	
0x0101	ERR_SEQUENCE	Sequence error. This is not a state in which a command can be received.	
0x0102	ERR_BIG	A packet is too large. (A receive buffer is insufficient.)	
0x0103	ERR_INVALID_PARAM	A parameter is illegal.	
/*0x1xxx: Processing e	rror in this unit*/		
0x1xxx	ERR_INTERNAL	Internal processing error in this unit	

Response ID	Definition of ID	Outline description (The detailed meaning varies depending on each command.)
/*Normal system*/		
0x0001	STAT_OK	
0x0002	STAT_BUSY	
/*Status of rush condition	ons*/	
0x0140	STAT_INVALID_MODEL	A model differs.
0x0141	STAT_INVALID_REGION	Destination differs.
/*Firmware data error*/		
0x0040	STAT_INVALID_DATA	The received firmware data is illegal (damaged).
		(The data is falsified and cannot be detected by CRC of a package file.)

A processing error in this unit is notified to a ResponseID field as an error.

CurStatus ID	Definition of ID	Outline description
0x0100	CURSTAT_PRE_INIT	Before CMD_INIT reception
0x0200	CURSTAT_PRE_SWITCHMODE	After CMD_SWITCHMODE reception

Command specifications

	Description						
CMD_GET_STATE	Outlin	• Outline					
	This command acquires the firmware update processing status in this unit.						
	*This command can be accepted at any time when communication is established.						
		mand parameter					
	None						
		onse (ID/Parameter)					
	-						
	ERR_						
		itialization succeeded. The subsequent r	naximum packet size a	ind minimum tim	ne-out are turned to a parameter.		
	Pa	arameter →	· · · · · ·				
		Parameter data arrangement	Size [Byte]	Туре			
		DK Parameter{					
		currentState ID	2	uint			
	}						
	• i	Meaning					
		currentState ID					
		This is the set state at the point of tim	ne where a command y	vas received			
		Refer to the ID list of each STAT ID.		ius recerveu.			
				DC annliastion i	annea a CMD. INUT assessed		
			e		ssues a CMD_INIT command		
					nmand cannot be returned by INIT		
		*From	n when PC application	issues a CMD_S	WITCH_MODE command		
	ERR_	PROV					
	Tł	his cannot be used for the communication	on protocol version set	to a packet heade	er.		
	N	o parameter					
	• Rema	urks					
CMD_INIT	Outlin	ne					
-	This	command initializes communication and	transfers the required	parameter			
		unit returns the internal state to the initi		e parameter.			
		e is a state in which the parameter canno	t be received.				
		mand parameter	Command parameter				
	None						
	None						
		onse (ID / Parameter)					
		onse (ID / Parameter)					
	Respo ERR_	onse (ID / Parameter)	naximum packet size a	nd minimum tim	e-out are turned to a parameter.		
	• Respo ERR_ In	onse (ID / Parameter) OK	naximum packet size a	nd minimum tim	e-out are turned to a parameter.		
	• Respo ERR_ In	onse (ID / Parameter) OK hitialization succeeded. The subsequent r arameter →	-		e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK iitialization succeeded. The subsequent r arameter → Parameter data arrangement	naximum packet size a Size [Byte]	nd minimum tim	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK uitialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{	Size [Byte]	Туре	ne-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK uitialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize	Size [Byte]	Type uint	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize	Size [Byte] 4 4 4	Туре	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	Size [Byte]	Type uint	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize	Size [Byte] 4 4 4	Type uint uint	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	Size [Byte] 4 4 4 4 4	Type uint uint uint	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	Size [Byte] 4 4 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.		
	Respo ERR_ In Pa	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	Size [Byte] 4 4 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.		
	• Respondent Respondent Participation Respondent R	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	Size [Byte] 4 4 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK ititialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse	Size [Byte] 4 4 4 4 4 4 4 4	Type uint uint uint uint	e-out are turned to a parameter.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize	Size [Byte] 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	Type uint uint uint uint			
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by	Size [Byte]	Type uint uint uint uint			
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	• Respondent	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize	Size [Byte]	Type uint uint uint uint uint	ion has succeeded.		
	• Respondent	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe	Type uint uint uint uint uint uint	ion has succeeded.		
	• Respondent	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packe	Type uint uint uint uint uint uint	ion has succeeded.		
	• Respondent	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded.	Size [Byte] 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each	Type uint uint uint uint uint et after initialization a command after of	ion has succeeded.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [n succeeded. The host must time out using a value	Size [Byte] 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each	Type uint uint uint uint uint et after initialization a command after of	ion has succeeded.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded. The host must time out using a value intervalBeforeCommand	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each e of more than the min	Type uint uint uint uint uint t after initialization a command after of imum timeout tim	ion has succeeded.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent rarameter → Parameter data arrangement DK Parameter { maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [rasucceeded. The host must time out using a value intervalBeforeCommand This is the min time [msec] required	Size [Byte] 4 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each e of more than the min	Type uint uint uint uint uint t after initialization a command after of imum timeout tim	ion has succeeded.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent r arameter → Parameter data arrangement DK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [r succeeded. The host must time out using a value intervalBeforeCommand This is the min time [msec] required intervalBeforeResponse	Size [Byte] 4 4 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each e of more than the min from when the host response to the sector of t	Type uint uint uint uint uint uint t after initialization a command after of imum timeout time ecceives a response	ion has succeeded. on has succeeded. communication initialization has ne. until it issues the next command.		
	Respondent Respondent In Pa C	onse (ID / Parameter) OK itialization succeeded. The subsequent rarameter → Parameter data arrangement DK Parameter { maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse Meaning maxCmdPacketSize This is the maximum packet size [by Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [by minTimeOut This is the minimum timeout time [rasucceeded. The host must time out using a value intervalBeforeCommand This is the min time [msec] required	Size [Byte] 4 4 4 4 4 4 4 te] of a command pack command te] of a response packet msec] common to each e of more than the min from when the host response to the sector of t	Type uint uint uint uint uint uint t after initialization a command after of imum timeout time ecceives a response	ion has succeeded. on has succeeded. communication initialization has ne. until it issues the next command.		

Command	Description						
CMD_INIT	ERR_PROV						
	This cannot be used for the communication protocol version set to a packet header.						
	No parameter						
	ERR_SEQUENCE						
	Communication sequence error. No	narameter					
	This is a state in which a CMD_INI'	command cannot be re	ceived.				
	Remarks						
MD_CHK_GUARD	• Outline						
	This command starts the confirmation	processing of rush condit	ions.				
	Command parameter						
	Parameter data arrangement	Size [Byte]	Туре				
	CHK_GUARD Parameter{						
	dataNo	4	uint				
	remainSize	4	uint				
	firmData	dataSize	Binary				
	}			-			
	 Meaning 						
	dataNo.						
	This is the number of times by wh	ich this command was iss	sued to confirm r	ish conditions. "0" is not used			
	Increment this from 1 irrespective						
	remainSize	or the existence of minib					
		.1 .1					
	This is the size of firmware data th	at has not been transmitt	ed yet. (The data	size becomes zero during final			
	transfer.)						
	This gives compatibility with the V	VRITE_FIRM command	described later.				
	firmData						
	IIImData		To confirm rush conditions, the top of firmware data (the data division of "FDAT" chunk) is split for transfer. The				
		p of firmware data (the d	ata division of "Fl	DAT" chunk) is split for transfer. Tl			
	To confirm rush conditions, the to						
	To confirm rush conditions, the to size of data to be transferred is spe						
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66.						
	To confirm rush conditions, the to size of data to be transferred is spe						
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66.	cified by windowSize. Op	peration is comple				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary	cified by windowSize. Op	peration is comple				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement	cified by windowSize. Op	peration is comple				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{	cified by windowSize. Op depending on response I Size [Byte]	Deration is comple				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize	cified by windowSize. Op depending on response I Size [Byte] 4	D D Type uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus	cified by windowSize. Op depending on response I Size [Byte]	Deration is comple				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D D Type uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus	cified by windowSize. Op depending on response I Size [Byte] 4	D D Type uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } {	cified by windowSize. Op depending on response I Size [Byte] 4 4 4	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { . Meaning	cified by windowSize. Op depending on response I Size [Byte] 4 4 4 2 2	D U U U U U U U U U U U U U U U U U U U				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that the	cified by windowSize. Op depending on response I Size [Byte] 4 4 4 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	D Type uint uint uint				
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { . Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { . Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 2 1 1 1 2 1 1 2 1 2 1 2 1 2 1 2 1 2 1 2 2 1 2 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { . Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 2 1 1 1 2 1 1 2 1 2 1 2 1 2 1 2 1 2 1 2 2 1 2 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { . Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 2 1 1 1 2 1 1 2 1 2 1 2 1 2 1 2 1 2 1 2 2 1 2 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condition	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_BUSY	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 2 1 1 1 1 1 1 1 2 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_OK STAT_BUSY STAT_INVALID_MODEL	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 4 32 4 32 4 32 4 4 4 4 4 4 5 2 5 5 6 8 8 8 8 8 8 8 9 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of 1 It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 1 2 1 1 1 1 1 1 1 2 2 1 2 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2	beration is comple	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_REGION	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 4 32 4 32 4 32 4 4 4 4 4 4 5 2 5 5 6 8 8 8 8 8 8 8 9 1 1 1 1 1 1 1 1 1 1 1 1 1	beration is complete D Type uint uint uint be received. indowSize + 8 (particular)	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_REGION STAT_INVALID_DATA	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1	be received. ndowSize + 8 (pa:	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1	be received. ndowSize + 8 (pa:	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1	be received. ndowSize + 8 (pa:	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally.	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1	be received. ndowSize + 8 (pa:	ted when STAT_OK is returned.			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_BUSY STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally. ERR_PROV	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 4 2 4 2 4 4 4 4 4 2 4 4 4 5 2 5 5 5 5 5 5 5 5 5 5 5 5 5	beration is comple	rameters other than firmData).			
	To confirm rush conditions, the to size of data to be transferred is spe *See pages 65 and 66. • Response (ID/Parameter) Common parameter that does not vary Parameter data arrangement Response Parameter{ windowSize numStatus for (i = 0; i < numStatus; i++){ Status ID } { • Meaning windowSize This is the size of firmData that th A packet (including firmData) of I It is necessary to satisfy packetSize numStatus This is the number of status IDs for Status ID Confirmation result of rush condit STAT_OK STAT_INVALID_MODEL STAT_INVALID_MODEL STAT_INVALID_DATA For OK and Busy, this is necessaril ERR_OK A command was received normally.	cified by windowSize. Op depending on response I Size [Byte] 4 4 2 2 4 32 4 2 4 2 4 4 4 4 4 2 4 4 4 5 2 5 5 5 5 5 5 5 5 5 5 5 5 5	beration is comple	rameters other than firmData).			

Command	Description					
CMD_CHK_GUARD	ERR_SEQUENCE					
	Communication sequence error. No param	neter.				
	This cannot be received before communication is initialized.					
	ERR_BIG					
	Packet size is too large.					
	ERR_INVALID_PARAM					
	dataNo is invalid. (A value is skipped.) dat	taSize is invalid.				
	Errors other than described above are process					
CMD_QUERY_VERSION	Outline	0				
- -	This command inquires the version of new an	nd old firmware.				
	Command parameter					
	None					
	 Response (ID/Parameter) 					
	ERR_OK					
	Normal termination. The version of new a	and old firmware is retu	rned using a para	meter.		
	Parameter →					
	Parameter data arrangement	Size [Byte]	Type	7		
	OK Parameter{	Size [Dyte]	Туре	-		
	oldFirmMinorVersion	2	uint	-		
	oldFirmMajorVersion	2	uint	-		
	newFirmMinorVersion	2	uint	-		
	newFirmMajorVersion	2	uint	-		
	}		unit	-		
	J					
	 Meaning 					
	oldFirmMinorVersion					
	oldFirmMajorVersion					
	Minor and major version numbers of	Minor and major version numbers of old firmware				
	newFirmMinorVersion					
	newFirmMajorVersion					
	Minor and major version numbers of	f new firmware				
	Fixed to 0x0000 before rush conditio	ons are confirmed. \rightarrow Th	ne version is not kr	nown yet.		
	ERR_PROV					
	This cannot be used for the communication	on protocol version set	to a packet header			
	No parameter					
	ERR_SEQUENCE					
	Communication sequence error. No param	neter.				
	This cannot be accepted before communic					
	Errors other than described above are processin					
CMD_SWITCH_MODE	Outline	0				
	This command performs switching to a firmw	vare update mode.				
	Command parameter					
	None					
	 Response (ID/Parameter) 					
	1 1					
	ERR_OK	A firmware update mode switching command is received normally.				
	ERR_OK A firmware update mode switching comm	and is received normal	lv.			
	A firmware update mode switching comm	and is received normal	lly.			
	A firmware update mode switching comm Parameter →			٦		
	A firmware update mode switching comm Parameter → Parameter data arrangement	aand is received normal Size [Byte]	Type	_		
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{	Size [Byte]	Туре			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0	Size [Byte]	Type uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	Size [Byte]	Type uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0	Size [Byte]	Type uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	Size [Byte]	Type uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	Size [Byte] 4 4	Type uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID	Size [Byte] 4 4	Type uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ OK Parameter{ reserved = 0 numStatus = 1 Status ID } • Meaning numStatus	Size [Byte]	Type uint uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID } • Meaning	Size [Byte]	Type uint uint uint			
	A firmware update mode switching comm Parameter → Parameter data arrangement OK Parameter{ OK Parameter{ reserved = 0 numStatus = 1 Status ID } • Meaning numStatus This is the number of statuses follow Status ID	Size [Byte]	Type uint uint uint to 1.)			

Command	Description				
CMD_SWITCH_MODE	ERR_PROV				
	This cannot be used for the communication protocol version set to a packet header.				
	No parameter				
	ERR_SEQUENCE				
	Communication sequence error. No pa	arameter.			
	This cannot be accepted while the app	lication of the main set	t is in operation and	when rush conditions are not	
	established.				
	Errors other than described above are in-s	set errors.			
CMD_WRITE_FIRM	Outline				
	This command rewrites firmware.				
	 Command parameter 				
	Parameter data arrangement	Size [Byte]	Туре		
	WRITE_FIRM Parameter{		/		
	dataNo	4	uint		
	remainSize	4	uint		
	firmData		Binary		
	}				
		II			
	 Meaning 				
	dataNo				
	This is the number of times by which	n this command was iss	sued to transfer firm	ware data. "0" is not used.	
	This is incremented every time firm	ware data is transferred	1.		
	This is reset by initialization of comm	nunication.			
	remainSize				
	This is the size of firmware data that	has not been transmitt	ted yet. (The data siz	e becomes zero during final	
	transfer.)				
	firmData				
	Firmware data (the data division of "	FDAT" chunk) is split	for transfer.		
	Firmware data (the data division of "FDAT" chunk) is split for transfer.				
	*See pages 65 and 66.				
	 Response (ID/Parameter) 	prending on response I	D		
	Response (ID/Parameter) Common parameter that does not vary de				
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	epending on response I Size [Byte]	D Type		
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{	Size [Byte]	Туре		
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize				
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1	Size [Byte] 4	Туре		
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize	Size [Byte]	Туре		
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1	Size [Byte] 4	Туре		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } 	Size [Byte] 4	Туре		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning 	Size [Byte] 4	Туре		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize 	Size [Byte] 4 2	Туре		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this	Size [Byte]	Type uint		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less A packet (including firmData) of less Common parameter (including firmData) Common parameter (includ	Size [Byte] 4 2 unit can receive. s than windowSize can	Type uint be received.	nators other than firmData)	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≥ It is necessary to satisfy packetSize I	Size [Byte] 4 2 unit can receive. s than windowSize can	Type uint be received.	neters other than firmData).	
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≧ Status ID }	Size [Byte] 4 2 unit can receive. s than windowSize can	Type uint be received.	neters other than firmData).	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of les It is necessary to satisfy packetSize ≥ Status ID Rewrite processing status 	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≥ Status ID Rewrite processing status STAT_OK Firmwa Firmwa Common parameter for the size of firm parameter for the size	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≥ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process 	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≥ Status ID Rewrite processing status STAT_OK Firmwa Firmwa Common parameter for the size of firm parameter for the size	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≥ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process 	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	Type uint be received. indowSize + 8 (parat		
	Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of les. It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress	Type uint be received. indowSize + 8 (parat		
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. 	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	Type uint be received. indowSize + 8 (paran	Шу.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic A packet for the	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	Type uint be received. indowSize + 8 (paran	Шу.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter 	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged.	Type uint be received. indowSize + 8 (paran	Шу.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_BUSY Process STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE 	Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version	Type uint be received. indowSize + 8 (paran	Шу.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter.	Type uint be received. indowSize + 8 (parately a set to a packet head	lly. er.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter.	Type uint be received. indowSize + 8 (parately a set to a packet head	lly. er.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_INVALID_DATA Firmwa STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter ERR_BIG	Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operatio	Type uint be received. indowSize + 8 (parately a set to a packet head	lly. er.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement Response Parameter{ windowSize numStatus = 1 Status ID } Meaning windowSize This is the size of firmData that this A packet (including firmData) of less It is necessary to satisfy packetSize ≧ Status ID Rewrite processing status STAT_OK Firmwa STAT_OK Firmwa STAT_OK Firmwa STAT_OK Firmwa STAT_INVALID_DATA Firmwa STAT_INVALID_DATA Firmwa ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No parameter ERR_BIG This could not be received because parameter STAT_BIG This could not be received because parameter STAT_STATURE Status Status STATURE Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status Status	Size [Byte] 4 2 unit can receive. s than windowSize can ≧ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operatio cket size is too large.	Type uint uint be received. indowSize + 8 (paran is terminated norma	lly. er.	
	 Response (ID/Parameter) Common parameter that does not vary de Parameter data arrangement	Size [Byte] 4 2 unit can receive. s than windowSize can ≥ 32 [byte] header + wi are rewrite processing i sing in progress are data is damaged. cation protocol version arameter. ate mode is in operatio cket size is too large. eceive buffer is insuffic	Type uint uint be received. indowSize + 8 (paran is terminated norma is terminated norma n and before rush co cient in capacity.	lly. er.	

Command	Description
CMD_WRITE_FIRM	ERR_INVALID_PARAM
	dataNo is invalid. (A value is skipped.) dataSize is invalid.
	Errors other than described above are errors in this unit.
	 Remarks
CMD_COMPLETE	• Outline
	This command notifies to confirm that firmware rewrite completion notification was accepted.
	Command parameter
	None
	•No response
	This unit is automatically restarted when this command is received.

Issuing the CMD_CHK_GUARD and CMD_WRITE_FIRM commands

Packet Header (Co	ommon in both a	command and	response)
-------------------	-----------------	-------------	-----------

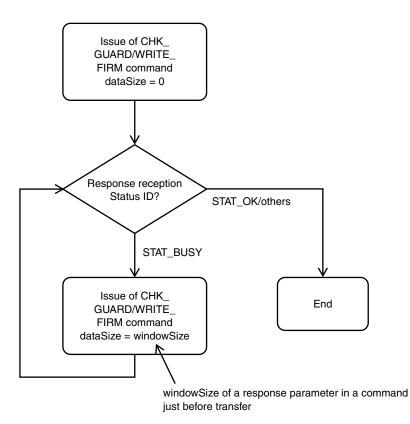
Data arrangement	Size [Byte]	Туре
Packet Header{		
BodySize	4	uint
Protocol Version	2	uint
Command ID	2	uint
Response ID	2	uint
Sequence No.	2	uint
reserved	4	uint
reserved	4	uint
reserved	4	uint
reserved	8	uint
}		

Command Parameter

Parameter data arrangement	Size [Byte]	Туре
CHK_GUARD Parameter{		
dataNo	4	uint
remainSize	2	uint
firmData	dataSize	Binary
}		

Parameter data arrangement	Size [Byte]	Туре
Response Parameter{		
windowSize	4	uint
numStatus	4	uint
for (i = 0; i < numStatus; i++){		
Status ID	2	uint
}		
}		

Firmware data is transferred from the host to the unit using CHK GUARD and WRITE_FIRM commands. For dataSize to be transferred, specify a value of less than windowSize set to the Response data that was issued just before transfer. When transmitting a command first, issue a command (with dataSize set to "0") without sending firmData and then issue a command for transferring data actually after confirming windowSize set to the Response data. Transmit data continuously until commands other than STAT_BUSY are returned.

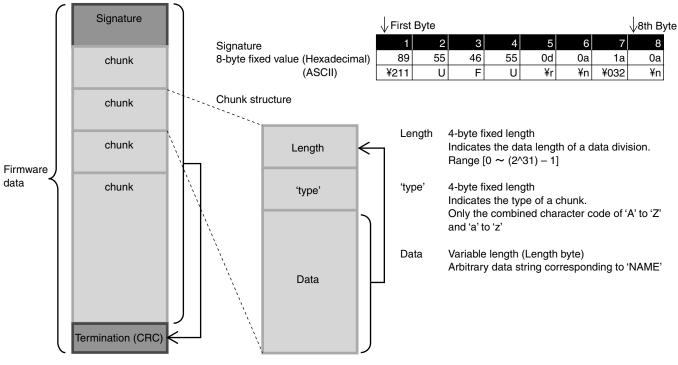


Discriminating the camera mode and updater mode

As described in the section of a UUD Firmware data structure, the USB PID, USB VID, and operating mode of equipment to be updated are described in the UDID chunk of firmware package data. The host to be updated confirms that USB PID and USB VID which acquired a USB descriptor from the unit are contained in the UDID chunk. By the ID operating mode, judge whether the unit is started in a camera mode or updater mode.

Structure of UUD Firmware data

- Signature is assigned to the top of data.
- One or more variable length chunk is continued after signature.
- A chunk containing a CRC32-calculated value is assigned to the termination of data.
- The byte order is based on a big-endian format. (MSB first)



Termination

Chunk indicating the termination data

The CRC-calculated value between the top of data (signature) and the chunk just before termination is stored.

For more details, see chunk list and detailed specifications. (page 66)

Chunk list and detailed specifications (Ver.1.0)

Description of type	
uint	Unsigned integer (Does not depend on the data length.)
Binary	Binary data string

Chunk type	Description					
DATV	Version of firmware data structure					
	Limiting conditions					
	This necessarily exists as a chunk at the top.					
	 Data arrangement 					
	Arrangement	Size [Byte]	Туре	Value		
	DATV Chunk{					
	length	4	uint	0x00000004		
	type	4	uint	'DATV'		
	firmDataVersion	2	uint			
	reserved	2	uint			
	}					
	Mandan					
	• Meaning					
	firmDataVersion					
	This indicates the protocol version of user firmware update.					
	Fixed to 0x0100.					
	reserved					
PROV	0x0000					
PROV	Communication protocol version of firmware update					
	Limiting conditions					
	This necessarily exists as the second chunk.					
	Data arrangement					
	Arrangement	Size [Byte]	Туре	Value		
	PROV Chunk{					
	length	4	uint	0x00000004		
	type	4	uint	'PROV'		
	firmProtocolVersion	2	uint			
	reserved = 0	2	uint	0x0000		
	}					
	- Mauring					
	Meaning Computer Number					
	firmProtocolVersion					
	This indicates the protocol version of user firmware update.					
	Fixed to 0x0100.					

	Description					
JDID	List of PID and VID corresponding to t	his unit to be updated in firmy	ware			
	 Limiting conditions 					
	This necessarily exists as a chunk.					
	Data arrangement					
	Arrangement	Size [Byte]	Туре	Value		
	UDID Chunk{					
	length	4	uint	4+id_count*8		
	type	4	uint	'UDID'		
	id_count	4	uint			
	/* Descriptor ID List */					
	for (i=0; i < id_count; i++){					
	PID	2	ID			
	VID	2	ID			
	Operating mode	1	uint			
	reserved = 0	3	uint	0x000000		
	}		unit			
	}					
				1		
	 Meaning 					
	id_count					
		omoon on din a VID on d DID				
	This is the number of lists in the c	orresponding vito and PID.				
	PID					
	This is the corresponding PID.					
	VID					
	This is the corresponding VID.					
	Operating mode					
	This is information for identifying whether PID and VID are used during application operation of a main					
	during updater mode operation.					
	ID during application operation o	f a main set: 0x01				
	ID during updater operation:	0x02				
DAT	Firmware data	0802				
Dill	Limiting conditions					
	-					
	This necessarily exists as a chunk.					
	Data arrangement		I			
	Arrangement	Size [Byte]	Туре	Value		
	FDAT Chunk{					
	length	4	uint			
	type	4	uint			
	Firmware data			'FDAT'		
	Firmware data	length	Binary	'FDAT'		
	}	length	Binary	'FDAT'		
	}	length	Binary	'FDAT'		
	Meaning	length	Binary	'FDAT"		
	}	length	Binary	'FDAT"		
END	Meaning		Binary	'FDAT"		
END	 Meaning Firmware data Chunk indicating the termination of data 		Binary	'FDAT"		
DEND	 Meaning Firmware data Chunk indicating the termination of date Limiting conditions 		Binary	'FDAT"		
DEND	 Meaning Firmware data Chunk indicating the termination of da Limiting conditions This necessarily exists as a chunk. 	ta	Binary	'FDAT"		
END	 Meaning Firmware data Chunk indicating the termination of da Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign 	ta	Binary	'FDAT"		
END	 Meaning Firmware data Chunk indicating the termination of data Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign Data arrangement 	ita nored.				
END	 Meaning Firmware data Chunk indicating the termination of data Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignedited as the stream after the strea	ta	Binary	'FDAT"		
END	 Meaning Firmware data Chunk indicating the termination of da Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign Data arrangement Arrangement DEND Chunk{ 	ita nored.				
END	 Meaning Firmware data Chunk indicating the termination of data Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignedited as the stream after the strea	ita nored.				
PEND	 Meaning Firmware data Chunk indicating the termination of da Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign Data arrangement Arrangement DEND Chunk{ 	nored.	Туре			
END	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length	tta nored. Size [Byte] 4	Type	Value		
DEND	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length type	ta nored. Size [Byte] 4 4 4	Type uint uint	Value		
DEND	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length type	ta nored. Size [Byte] 4 4 4	Type uint uint	Value		
DEND	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length type	ta nored. Size [Byte] 4 4 4	Type uint uint	Value		
END	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length type CRC }	ta nored. Size [Byte] 4 4 4	Type uint uint	Value		
Ð	} • Meaning Firmware data Chunk indicating the termination of da • Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ign • Data arrangement DEND Chunk{ length type CRC } • Meaning	ta nored. Size [Byte] 4 4 4 4 4 4 4 4 4 4 4 4 4	Type uint uint uint	Value 'DEND'		

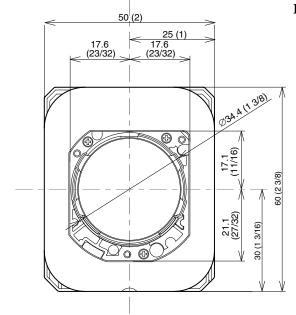
Specifications

Imager	1/2.5 Type "Exmor R" CMOS Sensor	
Picture elements	8510K pixels	
Lens	20× Zoom	
	f = 27 mm (Wide), 540 mm (Tele),	
	F2.0 to F3.8	
	Zoom movement speed	
	Optical Wide – Optical Tele	
	3.0 sec (Focus Tracking On)	
	Optical Wide – Super resolution	
	zoom Tele	
	3.4 sec	
	Digital Wide – Digital zoom Tele 5.0 sec	
	Focus Movement time	
	∞ to Near 0.1 sec	
Digital zoom	$12 \times (240 \times \text{ with optical zoom})$	
Angle of view (H)	-	
	Approx. 70.2 degrees (Wide end,	
	Image stabilizer Off)	
	Approx. 4.1 degrees (Tele end, Image	
	stabilizer Off)	
	Approx. 60.0 degrees (Wide end,	
	Image stabilizer On)	
	Approx. 3.5 degrees (Tele end, Image stabilizer On)	
Min. working dista		
C C	80 mm (Wide end), 800 mm (Tele end)	
Min. illumination		
(Typical)	0.4 lx (1/30 sec, 50%, High	
	Sensitivity mode On)	
	1.6 lx (1/30 sec, 50%, High	
	Sensitivity mode Off)	
	0.06 lx (1/4 sec (1/3 sec), 50%, High	
	Sensitivity mode On)	
	0.21 lx (1/4 sec (1/3 sec), 50%, High	
	Sensitivity mode Off)	
Sync system	Internal/External	
Recommended illu	umination	
	100 lx to 100,000 lx	
S/N ratio	50 dB (Weight On)	
Back light compen	isation	
-	On/Off	
Electronic shutter	-	
	1/1 sec to 1/10000 sec (22 steps)	

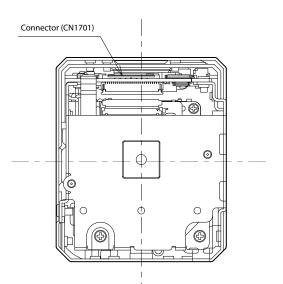
White Balance	Auto, ATW, Indoor, Outdoor, One Push WB, Manual WB, Outdoor Auto, Sodium Vapor Lamp (Fix/ Auto/Outdoor Auto)
Gain	Auto/Manual (0 to 48 dB (0 to 16 step))
	Max. Gain Limit (9 to 48 dB (3 to 12 step))
Noise Reduction	-
Defog mode	On/Off (Low, Mid, High)
Color Enhanceme	
	On/Off
Aperture control	16 steps
Preset	16-POSITIONS
Camera control IF	
	VISCA protocol (CMOS 3.1V)
	PTP USB 9.6 kbps, 19.2 kbps,
	38.4 kbps, 115.2 kbps, Stop bit,
	1 bit
Video Output	Digital (HDMI)
Storage temperatu	
0 1	-20 °C to +60 °C (-4 °F to +140 °F)/
	20% to 95%
	Absolute humidity: 36 g/m ³
Operating temperating	, e
1 0 1	–5 °C to +60 °C (23 °F to 140 °F)/
	20% to 80%
	Absolute humidity: 36 g/m^3
Power requirement	, e
1	6 V to 12 V DC
Power consumption	
1	3.0 W (When the motor operates:
	4.0 W)
Mass	Approx. 275 g (10 oz.)
Dimensions	$50 \times 60 \times 93.3 \text{ mm}$
	$(2 \times 2^{3}/_{8} \times 3^{3}/_{4} \text{ in.}) (w/h/d)$

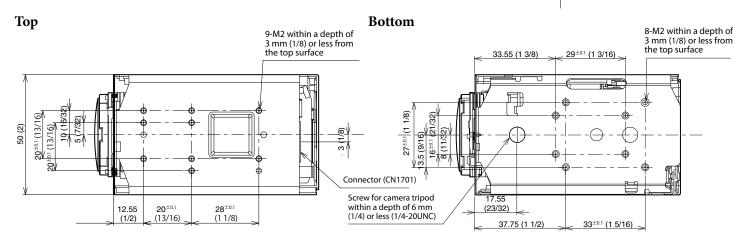
Dimensions

Front



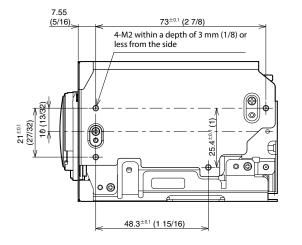
Back

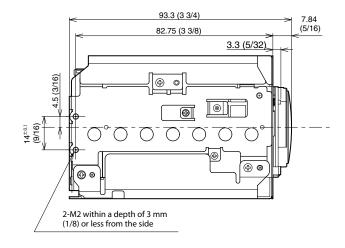




Left side

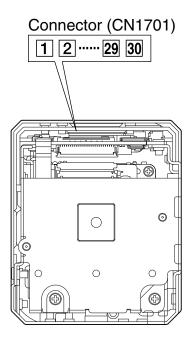
Right side





Unit: mm (inches)

Pin assignment



CN1701

KEL Co. USL00-30L-C

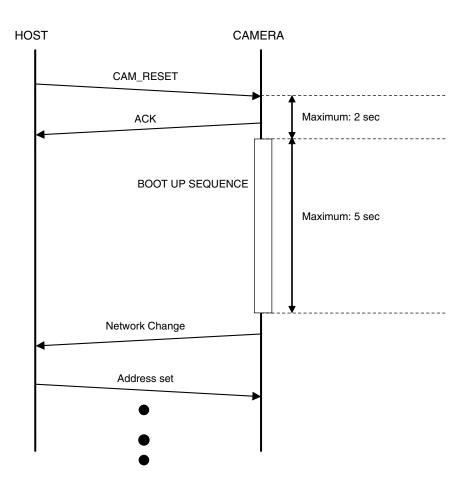
Pin No.	I/O	Name	Level
1	—	GND	
2	0	TMDS Clock –	
3	0	TMDS Clock +	
4	—	GND	
5	0	TMDS Data 0 –	
6	0	TMDS Data 0 +	
7	_	GND	
8	0	TMDS Data 1 –	
9	0	TMDS Data 1 +	
10	—	GND	
11	0	TMDS Data 2 –	
12	0	TMDS Data 2 +	
13	—	GND	
14	—	XSD0_ACC_LED	FCV-ES8250
15	—	EXT_SYNC	FCV-ES8250
16	—	EXT_SYNC_LOCK	FCV-ES8250
17	Ι	Hot Plug Detect	TMDS Out: 5V DC
			TMDS Stop: Open or GND
18	0	+ 5V Power	
19	Ι	USB_VBUS	USB communication active: 5 V DC
			USB communication
			inactive: Open or GND
20	—	GND	
21	I/O	USB_D –	
22	I/O	USB_D +	
23	—	GND	
24	Ι	VISCA_RxD	CMOS 3.1V
			(High: Min 2.3 [V],
			Low: Max 1.0 [V])
25	0	VISCA_TxD	CMOS 3.1V
			(High: Min 2.7 [V],
			Low: Max 0.4 [V])
26	Ι	RESET	Reset operation: Low (GND)
			Reset cancel: Open (High
			Impedance)
27	Ι	DC IN	6 to 12 V DC
28	Ι	DC IN	6 to 12 V DC
29	Ι	DC IN	6 to 12 V DC
30	Ι	DC IN	6 to 12 V DC

* It is assumed that Pin No. 18 is used as the 5 V power supply of HDMI.
* When you use the USB communication, connect VBUS of the USB host to Pin No. 19.

If you cannot prepare VBUS, connect Pin No. 18 to Pin No. 19.

Reset by Visca command

The time required from the end of camera reset to the issue of Network Change is as shown below.



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Please read the contents of description below at least once.

[linux-kernel] [busybox] [dosfstools] [e2fsprogs] [glibc] [hostname] [iptables] [procps] [util-linux-ng]

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[pcre]

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PCRE LICENCE

The basic library functions are written in C and are freestanding. Also included in the distribution is a set of C++ wrapper functions.

THE BASIC LIBRARY FUNCTIONS

Written by: Philip Hazel Email local part: ph10 Email domain: cam.ac.uk

University of Cambridge Computing Service, Cambridge, England.

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THE C++ WRAPPER FUNCTIONS

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End

[zlib]

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Jean-loup Gailly Mark Adler jloup@gzip.org madler@alumni.caltech.edu